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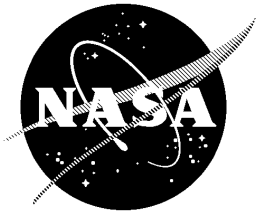
Landsat 7 System Zero-R Distribution Product Data Format Control Book Volume 5 Book 1

Revision 1

February 1998



National Aeronautics and Space Administration

Goddard Space Flight Center
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Landsat 7 System
Zero-R Distribution Product
Data Format Control Book
Volume 5
Book 1

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Section 1. Introduction

1.1 Identification

This document is the Data Format Control Book (DFCB) for the Landsat 7 Level 0 reformatted (0R) distribution product. It focuses on the Hierarchical Data Format (HDF) of the Landsat 7 0R product available from the Earth Resources Observation System (EROS) Data Center (EDC) Distributed Active Archive Center (DAAC).

1.2 Product Overview

The Landsat 7 system, unlike earlier Landsat programs, was not designed to produce high-level products for users, although a limited systematic correction capability has been added to the ground system. The primary user product is 0R data—an essentially raw data form that is marginally useful prior to radiometric and geometric correction. A Landsat 7 product, however, does contain all the ancillary data required to perform these corrections, including a calibration parameter file (CPF) generated by the Landsat 7 Image Assessment System (IAS). The CPF, which is updated at least four times a year, provides users with enhanced processing parameters for producing rectified image data of superior quality.

The product delivered to Landsat 7 data users is packaged in HDF, which is an open standard selected by the National Aeronautics and Space Administration (NASA) for Earth Observing System (EOS) data products. HDF is a self-describing format that allows an application to interpret the structure and contents of a file without outside information. HDF allows Landsat 0R products to be shared across different computer platforms without modification and is supported by a public domain software library consisting of access tools and various utilities.

1.3 Purpose

This DFCB provides the user with a high-level description of the Landsat 7 0R distribution product, the HDF structuring mechanisms employed, and a detailed layout of the image and ancillary data formats. Relevant HDF library routines and examples of 0R ingest programs will be added to this document.

To make full use of the data, the reader should also obtain the *Landsat 7 Science Data User's Guide* (Section 1.4, Applicable Document 11).

1.4 Applicable Documents

The documents listed below offer additional information pertaining to the Landsat Processing System (LPS) and its output data formats, HDF as designed by National Center for Supercomputing Applications (NCSA), and the EOS extensions to HDF.

1. Goddard Space Flight Center, Code 514.1, *Landsat 7 Processing System (LPS) Output Files Data Format Control Book*, December 1997
2. Lockheed Martin Missiles and Space, *Landsat 7 System Data Format Control Book (DFCB), Volume IV—Wideband Data*, Revision C, 23007702-IVC, May 29, 1997

3. Goddard Space Flight Center, Code 923, *Landsat 7 Calibration Parameter File Definition,* 430-15-01-002-0, September 1997

4. Hughes Applied Information Systems, Inc., *HDF-EOS Primer for Version 1*, EOSDIS, White Paper, 175-WK-001-001, April 1995

5. Hughes Applied Information Systems, Inc., *The HDF-EOS Swath Concept,* White Paper, WBS-WP-xxx-yyy (TBD), June 1995

6. Jet Propulsion Laboratory, California Institute of Technology, *Planetary Data System Standards Reference,* Chapter 12, "Object Description Language Specification and Usage," Version 3.2, July 24, 1995 (Web URL: http://pds.jpl.nasa.gov/stdref/chap12.htm)

7. University of Illinois at Urbana-Champaign, National Center for Supercomputing Applications (NCSA), *Getting Started with HDF,* Version 3.2, May 1993 (Web URL: http://hdf.ncsa.uiuc.edu/doc.html)

8. University of Illinois at Urbana-Champaign, National Center for Supercomputing Applications (NCSA), *HDF User's Guide,* May 1997 (Web URL: http://hdf.ncsa.uiuc.edu/doc.html)

9. University of Illinois at Urbana-Champaign, National Center for Supercomputing Applications (NCSA), *HDF Specification and Developer's Guide,* Version 3.2, September 1993 (Web URL: http://hdf.ncsa.uiuc.edu/doc.html)

10. University of Illinois at Urbana-Champaign, National Center for Supercomputing Applications (NCSA), *HDF Reference Manual,* Version 3.3, February 1994 (Web URL: http://hdf.ncsa.uiuc.edu/doc.html)

11. *Landsat 7 Science Data User's Guide* (in work, first draft available 2/98)

12. Goddard Space Flight Center, Code430, *Landsat 7 to International Ground Station (IGS) Interface Control Document,* Revision A, 430-11-06-009-A, September 30, 1997

13. Hughes Information Technology Systems, *Science User's Guide and Operations Procedures Handbook (Release B.0) for the ECS Project*, 205-CD-004-001, August 1997

Section 2. Pre-Archive Processing

A basic knowledge of the pre-archive ground processing will enable the user to better understand the 0R product.

The Landsat Ground Station (LGS) acquires Enhanced Thematic Mapper Plus (ETM+) wideband data directly from the Landsat 7 spacecraft by way of two 150-megabit-per-second (Mbps) X-band return links, separates each X-band data into two 75-Mbps channels (I and Q), and transmits the acquired wideband data over four 75-Mbps LGS output channels to the LPS. The LPS records all wideband data, at real-time rates, into its wideband data stores. A complete data set is represented by an I-Q channel pair. One channel holds bands 1 through 6, and the other holds bands 7 and 8 and a second gain form of band 6.

The LPS retrieves and processes each channel of raw wideband data, at lower than real-time rates, into separate accumulations of Earth image data, calibration data, mirror scan correction data (MSCD), and payload correction data (PCD). Channel accumulations represented by bands 1 through 6 and 6 through 8 become formats 1 and 2, respectively. PCD and MSCD are generated twice, once for each format. Their contents should be identical.

LPS spatially reformats Earth imagery and calibration data into Level 0R data. This involves shifting pixels by integer amounts to account for the alternating forward-reverse scanning pattern of the ETM+ sensor, the odd-even detector arrangement within each band, and the detector offsets inherent to the focal plane array engineering design. All LPS 0R corrections are reversible; the pixel shift parameters used are documented in the IAS CPF.

During LPS processing, format 1 bands are duplicated, radiometrically corrected, and used to assess cloud cover content and to generate browse. Cloud cover scores are generated on a scene-by-scene and quadrant-by-quadrant basis. Metadata are generated for the entire subinterval and on a scene-by-scene basis. The image data, PCD, MSCD, calibration data, and metadata are structured into HDF for each format and sent to the EDC DAAC for archiving in subinterval form. The two formats of data are united when a Landsat 7 0R product is ordered. The browse is sent to the EDC DAAC separately for use as an online aid to ordering.

Section 3. Product Types

Three sizing options, depicted in Figure 3–1, are available to a user when defining the size or spatial extent of a Landsat Level 0R product ordered from the EDC DAAC.

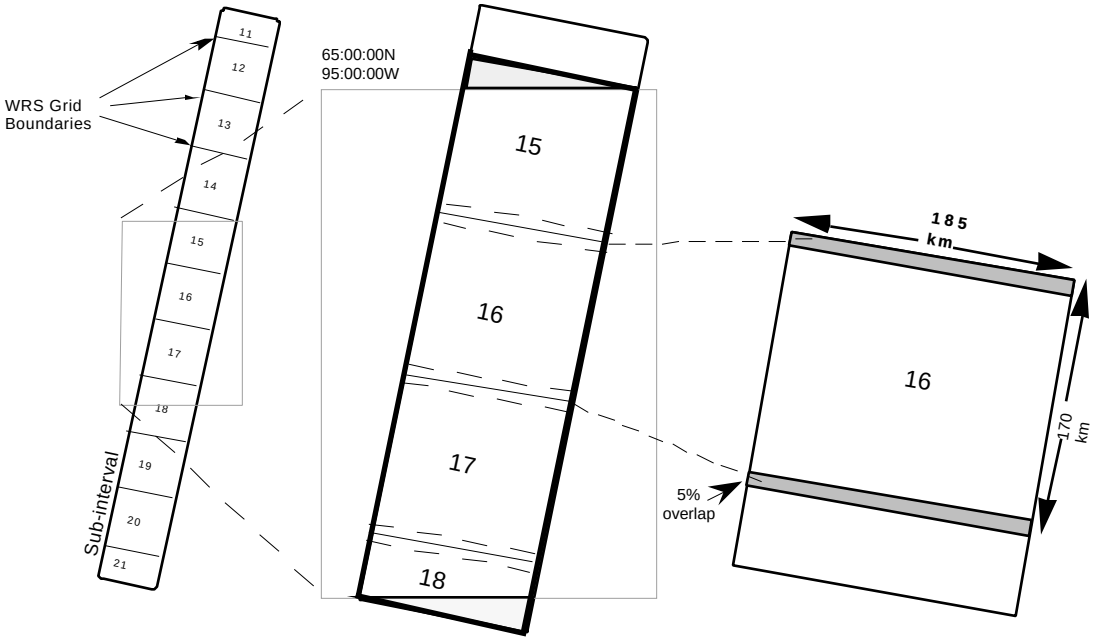

Figure 3–1. Level 0R Product Types

3.1 Standard Worldwide Reference System (WRS) Scene

The standard WRS scene as defined for Landsats 4 and 5 was preserved as an orderable product for Landsat 7. The WRS indexes orbits (paths) and scene centers (rows) into a global grid system comprising 233 paths by 248 rows. The path/row notation was originally employed to provide a standard designator for every nominal scene center and allow straightforward referencing without using longitude and latitude coordinates.

The distance between WRS center points along a path is 161.1 kilometers (km). A path distance of 85 km before and after a WRS center point defines the standard scene length or ground distance of 170 km. The standard WRS scene overlaps neighboring scenes along a path by 5 percent and has a width or cross-track distance of 185 km.

Landsat 7 browse is framed according to WRS scenes. An ordered scene will cover the same geographic extent observed in the browse. Standard WRS scenes have 375 scans. Partial scenes (less than 375 scans) may exist at the beginning or end of a subinterval because imaging events do not always start and end on scene boundaries. Browse and scene metadata for these occurrences accurately reflect their partial scene nature and geographic extent.

3.2 Subinterval

A subinterval of Landsat 7 data can be ordered in its entirety. An interval is a scheduled ETM+ image period along a WRS path, and may be from 1 to 90 full scenes in length. A subinterval is a

contiguous segment of raw wideband data received during a Landsat 7 contact period. Subintervals are caused by breaks in the wideband datastream due to communication dropouts and/or the inability of the spacecraft to transmit a complete observation (interval) within a single Landsat 7 contact period. The largest possible subinterval is 35 full scenes long with a partial scene preamble and postamble. The smallest possible subinterval is a single ETM+ scene.

3.3 Partial Subinterval

A partial Landsat 7 subinterval can also be ordered. The partial subinterval is dimensioned according to standard WRS scene width, is at least one half WRS scene in length (i.e., 182 scans), and can be up to an entire subinterval in length. A partial subinterval can float or be positioned at any scan starting point within a subinterval. Partial subintervals are defined by either specifying contiguous WRS locations or defining a bounding longitude/latitude rectangle on a computerized map display. In the latter case, all scans touched by the bounding rectangle are included in their entirety.

Section 4. Product Content Overview

A complete scene-sized 0R product ordered from the EDC DAAC consists of 19 data sets derived from the wideband telemetry, an IAS-generated CPF, a product-specific metadata file, a geolocation index generated by the EOS Data and Information System (EOSDIS) Core System (ECS), and an HDF directory. A brief description of each follows.

1–9. Earth image data. The unique bands of ETM+ image data comprise nine of the data sets. The data are laid out in a scan line sequential format in descending detector order (i.e., detector 16 followed by detector 15 and so on for the 30 meter bands). Individual band characteristics are listed in Table 4–1. Band 6 is captured twice, once in low-gain (6L) and the other in high-gain (6H) mode. Under nominal satellite configuration, the low-gain form of band 6 (6L) will be present in format 1.

Table 4–1. ETM+ Band Characteristics

Band Number	Wavelength (mμ)	Resolution (meters)	Data Lines per Scan	Data Line Length (bytes)	Bits per Sample
1	.450–.515	30	16	6,600	8
2	.525–.605	30	16	6,600	8
3	.630–.690	30	16	6,600	8
4	.775–.900	30	16	6,600	8
5	1.550–1.750	30	16	6,600	8
6L	10.40–12.50	60	8	3,300	8
6H	10.40–12.50	60	8	3,300	8
7	2.090–2.35	30	16	6,600	8
8	.520–.900	15	32	13,200	8

10. Internal calibrator (IC) data—format 1. IC data for format 1 consist of scan line ordered internal lamp and shutter data for bands 1 through 5 and blackbody radiance and shutter data for band 6L. The data are collected once per scan and structured in a band sequential format in descending detector order (e.g., detector 16 followed by detector 15 and so on for the 30-meter bands).

11. IC data—format 2. IC data for format 2 consist of scan-ordered internal lamp and shutter data for bands 7 and 8 and blackbody radiance and shutter data for band 6H. The data are collected once per scan and structured in a band sequential format in descending detector order (e.g., detector 16 followed by detector 15 and so on for the 30-meter bands).

12. MSCD—format 1. A logical record of MSCD exists for each data scan present in the 0R product ordered. Each logical record consists of three MSCD data values—the first half scan error, the second half scan error, and the scan line direction. This information, which actually applies to the previous scan, is used to compute deviations from nominal scan mirror profiles as measured on the ground and reported in the CPF. Also included in the MSCD file are scan-based values such as time code, gain status, and processing errors encountered by LPS. The MSCD are trimmed to fit

the product ordered although one additional record is added to the file during the subsetting process because scan error and direction information corresponds to the previous scan.

13. MSCD—format 2. A duplicate set of MSCD is generated when format 2 is processed and is kept with the product in the event format 1 MSCD is lost or corrupted.

14. PCD—format 1. The PCD for format 1 consist of attitude and ephemeris profiles as well high-frequency jitter measurements. PCD for the entire subinterval are included with the 0R product regardless of the size of the data set ordered.

15. PCD—format 2. A duplicate set of PCD is generated when format 2 is processed and is kept with the product in the event format 1 is lost or corrupted.

16. Scan line offsets—format 1. During LPS processing, image data are shifted in an extended buffer to account for predetermined detector and band shifts, scan line length, and possible bumper wear. The scan line offsets represent the actual starting and ending pixel positions for valid (nonzero fill) Earth image data on a data-line-by-data-line basis for bands 1 through 6L. The left starting pixel offsets also apply to the IC data.

17. Scan line offsets—format 2. During LPS processing, image data are shifted in an extended buffer to account for predetermined detector and band shifts, scan line length, and possible bumper wear. The scan line offsets represent the actual starting and ending pixel positions for valid (nonzero fill) Earth image data on a data-line-by-data-line basis for bands 6H through 8. The left starting pixel offsets also apply to the IC data.

18. Metadata—format 1. During LPS format 1 processing, metadata is generated that characterizes the subinterval's spatial extent, content, and data quality for bands 1 through 6L. This file, in its entirety and original form, accompanies the 0R product.

19. Metadata—format 2. Format 2 metadata is similar but not identical to format 1 metadata. The subinterval-related metadata contents are identical; the scene-related metadata are specific to bands 6H, 7, and 8. Also, the format 2 metadata do not include cloud cover assessment data or references to browse data products. This file, in its entirety and original form, accompanies the 0R product.

20. Metadata—ECS. A third metadata file is generated by ECS during order processing. This file contains product-specific information such as corner coordinates and the number of scans.

21. Geolocation index. The geolocation index is also produced by ECS. This table contains scene corner coordinates and their product-specific scan line numbers for bands at all three resolutions. Its purpose is to provide for efficient subsetting of a 0R product.

22. Calibration parameters. The IAS regularly updates the CPF to reflect changing radiometric and geometric parameters required for Level 1 processing. These are stamped with applicability dates and sent to the EDC DAAC for storage and bundling with outbound 0R products.

23. HDF directory. A file containing all the pointers, file size information, and data objects required to open and process the 0R product using the HDF library and interface routines.

A user may order a subset of the available bands that will affect the actual file count in a 0R product. In all cases, however, every product includes two PCD files, two MSCD files, three metadata files, the CPF, and the HDF directory. Only the internal calibrator, scan line offset, and

Earth image file counts are affected by a product possessing less than the full complement of bands.

Section 5. Data Definition

5.1 HDF Conventions

5.1.1 File Structure

The 0R product files are created using the HDF function library developed by NCSA. The product's design allows users to choose either low- or high-level programming tools from NCSA's HDF libraries. The product design does not preclude a user from developing original code for product access. All files are simple byte streams. There are no data records as such. Information about the basic structure of HDF files can be found in various NCSA and NASA publications listed in Section 1.4, Applicable Documents.

New users should begin with *Getting Started with HDF*, which provides an introduction to the concepts used in HDF file design and programming and will give the reader an appreciation for the design philosophy of the HDF software and file structure. Additionally, the *HDF User's Guide* and *HDF Reference Manual* are excellent resources for the HDF programmer. More advanced users can read *NCSA HDF Specifications and Developer's Guide* to learn about the low-level structure of HDF files.

5.1.2 Data Definition Terminology

Data structures are referred to using HDF terminology. Descriptions of structures relevant to the 0R product follow:

Scientific Data Set (SDS)—An array of data of any fixed dimensionality (rank) from 1 to 32767 and any one data type.

Vdata—A record-based structure where values are stored in fixed-length fields. Fields are defined, named, and typed individually. All records within a Vdata are identical in structure.

Vgroup—A structure for associating sets of data objects. Vgroups define logical relationships and may contain any HDF objects, including other Vgroups.

External Element—Data stored in a separate file, external to the basic HDF file. External elements allow for larger product sizes (e.g., up to 12 scenes) and the ability to read 0R products without using the HDF library.

5.1.3 Data Representation

Data are both binary and American Standard Code for Information Interchange (ASCII). Bit and byte ordering follow the Institute of Electrical and Electronics Engineers (IEEE) conventions. The term byte is synonymous with octet as used by the International Organization for Standardization (ISO).

5.1.4 Notation

Storage types are referred to using HDF number type nomenclature:

type#

where type is either char (character), int (integer), or float (floating point), and # is a decimal count of the number of bits used to represent the data type. The type mnemonics *int* and *char* may be preceded by the letter u, indicating an unsigned value. For example, the data type *uint32* refers to an unsigned 32-bit integer value.

Storage types relevant to the 0R product are as follows:

Data Type	HDF Nomenclature
8-bit character	char8
8-bit unsigned integer	uint8
16-bit signed integer	int16
16-bit unsigned integer	uint16
32-bit signed integer	int32
32-bit floating point number	float32
64-bit floating point number	float64

5.2 Structure Overview

The 0R product is packaged and distributed as a collection of external elements with an HDF data directory. It can be as large as 35 full scenes or as small as a 182-scan half scene. External elements are distinguished by the fact that they exist as separate files and contain only data. Information about their HDF structure and interrelationships can be found in the HDF directory.

The number of files or external elements composing a 0R product can vary according to product size (e.g., partial subinterval, subinterval) and the number of bands ordered. Assuming both subinterval formats have been archived, the following 10 files always accompany a 0R product:

1. HDF data directory
2. MSCD—format 1
3. MSCD—format 2
4. PCD—format 1
5. PCD—format 2
6. Metadata—format 1
7. Metadata—format 2
8. Metadata—ECS specific
9. Calibration parameter file
10. Geolocation index

The Earth image data, IC data, and the scan line offset product components affect the file total in the following ways:

- Each Earth image band ordered is self contained in a single file. The lone exception to this one-file-per-band rule occurs whenever a partial subinterval is ordered that is both greater than 12 scenes and includes the panchromatic band (band 8). Due to an HDF file size

restriction, the panchromatic band must be allocated to 2 gigabyte (GB) files. A 35-scene subinterval would thus require 3 such files or image segments.

- During LPS processing, IC bands 1 through 6L are arranged in band sequential order in one file, while bands 6H through 8 are arranged in similar fashion in a second file. The IC data are subset according to scan lines and bands ordered yet adhere to the band sequential two-file arrangement. For example, a product consisting of just one band would have a single IC file containing that band's pulse and shutter data. A product of nine bands includes the full complement of IC data in two files. And a product with only two bands from different formats has two IC files with a single band each.

- Also during LPS processing, the starting and ending pixel numbers or scan line offsets are computed on a data-line-by-data-line basis for each band. These are stored in a separate file for each band by LPS but are repackaged by ECS in a band sequential two-file arrangement similar to the IC data. The scan line offsets that accompany a 0R product are specific to ordered bands only.

The collection of external elements that compose a complete single scene 0R product is conceptualized in Figure 5–1. The nine bands of Earth image data are represented by nine SDS external elements. Bands sharing a common ground resolution are logically associated using the Vgroup data structure. Three Vgroups result: bands 1 through 5 and 7, bands 6L and 6H, and band 8.

The nine bands of IC data follow an identical structure. Three groups are formed based on a common ground resolution. Two external elements are used to store the IC data. One file contains bands 1 through 6L, and the other contains bands 6H, 7, and 8.

The scan line offsets from format 1 and 2 are stored as two Vdata tables. One file contains the offsets for bands 1 through 6L and the other contains bands 6H through 8. The Vdata for each band is logically associated with its corresponding Earth image and IC SDS.

One geolocation index Vdata accompanies the product. Although the geolocation Vdata exists as a separate file, it is logically associated with each image and IC band using the Vgroup data structure.

The MSCD from formats 1 and 2 are stored as two Vdata tables and are logically grouped using the Vgroup data structure.

The PCD from formats 1 and 2 are stored as Vdata tables and also are logically united.

The product also contains the two LPS-generated metadata files and an ECS-generated metadata file that is crafted during product generation. Metadata are stored as a Vdata table with one long ASCII-character field or string. The metadata files follow the ODL syntax.

The last element of the file is the IAS-generated calibration parameters. Calibration parameters are stored in a Vdata table composed of three-row ASCII-character fields or strings using the ODL syntax.

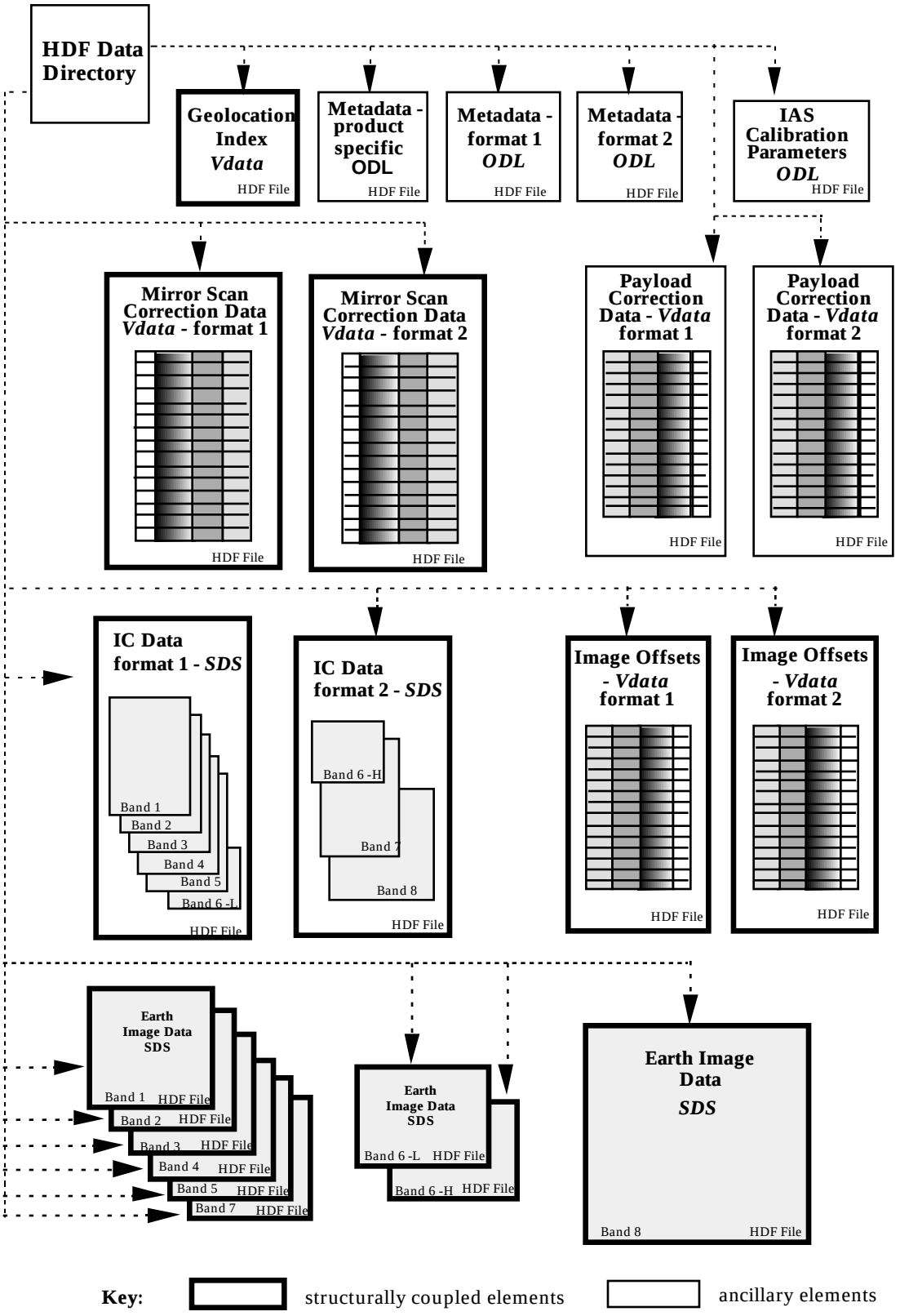

Figure 5–1. A Complete 0R Scene Product—External Elements

5.3 Detailed Structure

5.3.1 Naming Conventions

All of the HDF data structure names, except the CPF, are derived using the following LPS file naming notation:

"L7XsssfnYYDOYHHuuv.xxx"

where

L7 indicates the Landsat 7 mission.

X is 1, 2, or 3 for the Landsat 7 X-band used to downlink data to the LGS.

1 = XL (low frequency), 2 = XM (medium frequency), and 3 = XH (high frequency). This is the normal mapping of the numerical value of the capture source in the configuration table. For files received on tape from AGS (Alaska) and SGS (Svalbard, Norway), the current value of the string will be used unless specified otherwise.

sss indicates the ground station such as EDC at Sioux Falls, AGS, or SGS.

The international ground station (IGS) identifier code is used for tapes received from other downlink sites. These codes can be found in the Landsat 7 to IGS Interface Control Document (ICD) (see Section 1.4, Applicable Document 12).

f indicates ETM+ data format (1 or 2). (The geolocation table defaults to 1.)

n indicates LPS processor number (1–9).

YY indicates the last two digits of the year associated with a contact period (not acquisition time).

DOY is the Julian day of year of the contact period.

HH is the hour of the contact period within a 24-hour day (00–23).

uu indicates a subinterval number within this contact period (01–99).

v indicates the data set version number (v = 0 for original or 1–9 for reprocessed data).

xxx indicates the type of data (MSD for MSCD, PCD for PCD, GEO for the geolocation index B10 through B83 for Earth image data, C10 through C80 for the IC data, and O10–O80 for the scan line offsets).

The CPF data structure name is derived from the CPF file name assigned by IAS. Its notation is as follows:

L7CPFYYYYMMDD_YYYYMMDD.nn

where YYYYMMDD is the effective start date and effective end date, respectively, and nn is the incrementing number within a 90-day period (00–99).

It is important to distinguish between the HDF data object names described above and the names of the external elements (i.e., physical files). The file names described in Section 5.3.4.2 and presented in example form in Section 5.3.4.4.3 are derived from the HDF data object names and include a unique ECS-assigned file extension. The file names are also stored in the HDF directory.

5.3.2 SDS Definitions

ETM+ imagery data, both Earth and calibration, are structured as SDSs. During 0R processing, a fill pattern is used to distinguish good data from bad data. Odd detectors are filled with 0s (00000000), while even detectors are filled with 255s (11111111). Data-filling is performed on a minor frame basis—if data are missing from part of a minor frame, the entire minor frame is filled. Table 5–1 lists the individual SDSs that compose the 0R product.

Table 5–1. Level 0R SDSs (1 of 2)

No.	SDS Name	Description	Number Type	Rank	Dimensions
1	"L7Xsss1nYYDOYHHuuv.B10"	SDS containing 30-meter ETM+ band 1 Earth image data	uint8	2	Scan line count * 16 by 6600 (row major)
2	"L7Xsss1nYYDOYHHuuv.B20"	SDS containing 30-meter ETM+ band 2 Earth image data	uint8	2	Scan line count * 16 by 6600 (row major)
3	"L7Xsss1nYYDOYHHuuv.B30"	SDS containing 30-meter ETM+ band 3 Earth image data	uint8	2	Scan line count * 16 by 6600 (row major)
4	"L7Xsss1nYYDOYHHuuv.B40"	SDS containing 30-meter ETM+ band 4 Earth image data	uint8	2	Scan line count * 16 by 6600 (row major)
5	"L7Xsss1nYYDOYHHuuv.B50"	SDS containing 30-meter ETM+ band 5 Earth image data	uint8	2	Scan line count * 16 by 6600 (row major)
6	"L7Xsss1nYYDOYHHuuv.B60"	SDS containing 60-meter ETM+ band 6L Earth image data	uint8	2	Scan line count * 8 by 3300 (row major)
7	"L7Xsss2nYYDOYHHuuv.B60"	SDS containing 60-meter ETM+ band 6H Earth image data	uint8	2	Scan line count * 8 by 3300 (row major)
8	"L7Xsss2nYYDOYHHuuv.B70"	SDS containing 30-meter ETM+ band 7 Earth imagery	uint8	2	Scan line count * 16 by 6600 (row major)
9	"L7Xsss2nYYDOYHHuuv.B81"	SDS containing ETM+ band 8 15-m data, 1- or more segment product	uint8	2	Scan line count * 32 by 6600 (row major)
10	"L7Xsss2nYYDOYHHuuv.B82"	SDS containing ETM+ band 8 15-m data, 2- or more segment product	uint8	2	Scan line count * 32 by 6600 (row major)
11	"L7Xsss2nYYDOYHHuuv.B83"	SDS containing ETM+ band 8 15-m data, 3-segment product	uint8	2	Scan line count * 32 by 13200 (row major)
12	"L7Xsss1nYYDOYHHuuv.C10"	SDS containing ETM+ band 1 calibration data	uint8	2	Scan line count * 16 by 1380 (row major)
13	"L7Xsss1nYYDOYHHuuv.C20"	SDS containing ETM+ band 2 calibration data	uint8	2	Scan line count * 16 by 1380 (row major)

Table 5–1. Level 0R SDSs (2 of 2)

No.	SDS Name	Description	Number Type	Rank	Dimensions
14	"L7Xsss1nYYDOYHHuuv.C30"	SDS containing ETM+ band 3 calibration data	uint8	2	Scan line count * 16 by 1380 (row major)
15	"L7Xsss1nYYDOYHHuuv.C40"	SDS containing ETM+ band 4 calibration data	uint8	2	Scan line count * 16 by 1380 (row major)
16	"L7Xsss1nYYDOYHHuuv.C50"	SDS containing ETM+ band 5 calibration data	uint8	2	Scan line count * 16 by 1380 (row major)
17	"L7Xsss1nYYDOYHHuuv.C60"	SDS containing ETM+ band 6L calibration data	uint8	2	Scan line count * 8 by 690 (row major)
18	"L7Xsss2nYYDOYHHuuv.C60"	SDS containing ETM+ band 6H calibration data	uint8	2	Scan line count * 8 by 690 (row major)
19	"L7Xsss2nYYDOYHHuuv.C70"	SDS containing ETM+ band 7 calibration data	uint8	2	Scan line count * 16 by 1380 (row major)
20	"L7Xsss2nYYDOYHHuuv.C80"	SDS containing ETM+ band 8 calibration data	uint8	2	Scan line count * 32 by 2760 (row major)

5.3.3 Vdata Definitions

Vdata structures are employed to store MSCD, PCD, scan line offsets, metadata, and geolocation information for the product. All 0R Vdatas are designated full interlace, which organizes the Vdata on a record-by-record basis. This mode allows additional records to be appended.

5.3.3.1 MSCD Vdata

The number of MSCD Vdata records is equal to the number of data scans in the product plus one. The additional record is included because several fields reference the previous scan line. The spacecraft time associated with each ETM+ scan is provided in seconds since January 1, 1993, and is a Julian day, time-of-day format. The former is required for ECS software.

The Vdata format for the MSCD is neutral with respect to format 1 and format 2 data. The LPS should produce mirror copies of the MSCD file for both formats if they are received with the same MSCD minor frame words with the same errors.

Under noisy data input and poor data synchronization conditions, the values for most MSCD fields are generated through flywheel and interpolative methods. The MSCD fields scan_no and Time are examples of two such fields that can always be determined even if a major frame is entirely filled. However, some MSCD fields require fill patterns and/or flags in the event of an entirely filled ETM+ major frame. These are the gain_status, mux_assembly_id, and cal_shutter_status fields. Their fill and flag values are listed below. Other affected fields that will be filled with a zero value include the eol_location, fhs_vote, fhs_err, shs_vote, shs_err, cadu_sync, scan_sync, cadus/vcdus_received, fly_wheel_cadus, bit_slip_cadus, r-s_err-cadus, bch_corrected_vcdus, bch_uncorrected_vcdus, and minf_filled fields.

Table 5–2 lists the contents of the MSCD Vdatas for either format 1 or 2.

Table 5–2. MSCD Vdata—Format 1 or 2 (1 of 5)

Vdata Name: "L7XsssfnYYDOYHHuuv.MSD"
Vdata Class: LPS_MSCD
Interlace Type: FULL_INTERLACE
Bytes Per Logical Record: 85
Number of Records: One record per product scan line (major frame)

Field Name	Number Type	Order	Description	Remarks
scan_no	uint16	1	Subinterval scan line counter values = 1–11725	Provides a sequence counter for the ETM+ scans (major frames) contained in a 0R product. This counter is referenced relative to the original subinterval, not the product ordered.
Time	float64	1	ETM+ scan time in seconds since midnight January 1, 1993, rounded to 7 decimal places	Time code conversion from scan_timecode (see next entry). ECS required time format.
scan_timecode	char8	25	Scan line time of the format YYYY:ddd:hh:mm:ss:ttttttt where YYYY = 4-digit Julian year ddd = Day (01–366) hh = Hours (00–23) mm = Minutes (00–59) ss = Seconds(00–59) ttttttt = Fractional seconds [0–9999375, where the clock cycle is 1/16 millisecond (ms)]	The ETM+ scan start time extracted from the timecode minor frames of the ETM+ major frame data reported in this data record. A computed scan start time is provided if a valid time is not available from the time code minor frames. Time is expressed using the Greenwich Mean Time (GMT) standard.
timecode_flag	uint8	1	Valid timecode flag, where 0 = Valid timecode, 1 = Computed timecode	
eol_flag	uint8	1	Flag for valid end of line (EOL) pattern code: 0 = Valid pattern in expected minor frame location 1 = Missing EOL. The EOL pattern is not found at all. 2 = Valid pattern is found inside the user-specified range but outside the nominal range.	An EOL code is needed by LPS to start calibration data extraction. If an EOL is missing, the nominal scan line length will be assumed. In this way, the pixel data may be salvaged, but the flag is needed to warn users that it may be suspect. However, calibration data would need to be filled because there is no way of knowing just where that started. A user-specified parameter gives the bilateral search zone around the nominal location for the EOL marker. The nominal range for the EOL marker is given in the eol_location field description.

Table 5–2. MSCD Vdata—Format 1 or 2 (2 of 5)

Field Name	Number Type	Order	Description	Remarks
eol_location	uint16	1	Minor frame location (number in the range: 6318–6323) The minor frame location (number) within a major frame that contains the first word of the ETM+ EOL code. The eol_flag reports eol_location errors.	The EOL is expected to occur within the vicinity of minor frame number 6,320 in each ETM+ major frame. The EOL code consists of two adjacent minor frames. The EOL indicates an end of the active scan period and start of a calibration data period past the scan line data (SLD) words. If eol_flag = 1, LPS supplies the nominal location for eol_location.
scan_dir_vote	uint8	1	Scan direction majority vote quality 0 = All bits in all scan direction word groups are equal. 1 = At least 1 bit in the scan direction word groups is not equal to the other bits. 2 = Scan direction is not found for a missing and/or an entirely filled scan and is therefore interpolated from the previous scan if possible or is classified as unknown.	A majority vote quality of 1 may indicate an error with the received and/or decoded scan direction value (back to back forward or reverse scans).
scan_dir	char8	1	Scan direction character F = Forward scan R = Reverse scan U = Unknown	The ETM+ scan direction is interpolated from SLD minor frames of the first valid ETM+ major frame. This scan direction is for the previous scan (major frame). If the scan direction is Unknown, the default Forward direction will be used for placing the data.
fhs_vote	uint8	1	First half scan (FHS) error majority vote quality 0 = All bits in each FHS error word group are equal. 1 = At least 1 bit in at least one FHS error word group is not equal to other bits in the group.	A value of 1 indicates that the received/decoded fhs_err value is probably erroneous.
fhs_err	int16	1	FHS error count: –2048 to 2047 This is a 12-bit number provided in an int16 field using two’s complement notation.	The FHS error is interpolated from the SLD minor frames of the ETM+ major frame. This value is for the previous scan.

Table 5–2. MSCD Vdata—Format 1 or 2 (3 of 5)

Field Name	Number Type	Order	Description	Remarks
shs_vote	uint8	1	Second half scan (SHS) error majority vote quality 0 = All bits in each SHS Error word group are equal. 1 = At least 1 bit in at least one SHS error word group is not equal to other bits in the group.	A value of 1 indicates that the received/decoded shs_err value is probably in error.
shs_err	int16	1	SHS error count: -2048 to 2047 This is a 12-bit number provided in an int16 field using two's complement notation.	The SHS error is interpolated from the SLD minor frames of the ETM+ major frame. This value is for the previous scan.
gain_status	char8	9	"ggggggggg" where g's identify bands 123456678 for both formats = 123456$$$ for format 1 = $$$$$$678 for format 2 where $ identifies unused fields g = L indicates a low-gain state g = H indicates a high-gain state g = Ns in all band positions indicates that gain values could not be found due to an entirely filled major frame.	For each band, the gain status is defined by the gain state value in the "PCD/Status Data" field of the first error-free virtual channel data unit (VCDU) containing data for the scan.
gain_change	char8	9	"ggggggggg" where g's identify bands 123456678 for both formats = 123456$$$ for format 1 = $$$$$$678 for format 2 g = 0 in a band position indicates no gain change since last scan g = + in a band position indicates a gain from low to high g = – in a band position indicates a gain change from high to low	This value is 0 if it is the first scan of a subinterval.
mux_assembly_id	uint8	1	= 0–7, for Landsat 7 multiplexer assemblies 0–7 or = 9 to indicate that the mux_assembly_id value could not be extracted from an entirely filled major frame.	Identifies the Landsat 7 spacecraft onboard multiplexer used in the ETM+ dataflow for this major frame. The multiplexer status is obtained from the first error-free channel access data unit (CADU)/VCDU used in the construction of this major frame.

Table 5–2. MSCD Vdata—Format 1 or 2 (4 of 5)

Field Name	Number Type	Order	Description	Remarks
cal_shutter_status	uint8	1	0 = Primary shutter 1 = Backup shutter or = 9 to indicate that the cal_shutter_status value could not be extracted from an entirely filled major frame.	Identifies the Landsat 7 spacecraft internal calibration shutter status during the ETM+ data flow for this major frame. The CAL shutter status is obtained from the first error-free CADU/VCDU used in the construction of this major frame.
cadu_sync	uint8	1	Flag to indicate loss of CADU sync anywhere within the scan 0 = No loss 1 = Sync loss	A sync loss condition indicates potential loss of minor frame data requiring LPS to use fill data in completing a major frame.
scan_sync	uint8	1	Flag for valid sync for current major frame 0 = Valid sync 1 = Flywheeled sync	Valid sync = Line sync code was correctly found and decoded as specified in the Landsat 7 DFCB. Flywheeled sync: The sync in the current scan is forced "True" because the line sync code minor frame could not be correctly found and/or decoded as specified in the Landsat 7 DFCB. The presence of the line sync code was "deduced" from correctly finding/decoding the time code minor frames of an ETM+ major frame.
minf_faults	char8	1	An index (hexadecimal 0 through D) representing the number of minor frame faults (m) in the range: "0" for no faulty minor frames "1" for 1 <= m <=2 "2" for 3<= m <= 4 "3" for 5<= m <= 8 "4" for 9 <= m <= 16 "5" for 17 <= m <= 32 "6" for 33 <= m <= 64 "7" for 65 <= m <= 128 "8" for 129 <= m <= 256 "9" for 257 <= m <= 512 "A" for 513 <= m<= 1024 "B" for 1025 <= m <= 2048 "C" for 2049 <= m <= 4096 "D" for 4097 <= m <= NNNN NNNN is an LPS operator-selectable parameter for the maximum number of minor frames possible in an ETM+ major frame.	This quality index is computed by LPS on a major frame basis. This index provides a quicklook assessment on the number of faulty minor frames contained in a major frame. Faulty minor frames contain fill data or are extracted from VCDUs containing uncorrected BCH errors. Lower quality indices indicate better quality major frames. Without bumper wear, there is a nominal of 7,423 minor frames in an ETM+ major frame. Accounting for 17 (TBR) minor frames of bumper wear on each end of the scanner, there could be a maximum of 7,457 (TBR) minor frames in an ETM+ major frame.

Table 5–2. MSCD Vdata—Format 1 or 2 (5 of 5)

Field Name	Number Type	Order	Description	Remarks
cadus/vcdus_ received	uint16	1	= 0–650 Approximately 643 VCDUs are required to build one ETM+ major frame (~7,423 minor frames).	The number of VCDUs used to construct this ETM+ major frame.
fly_wheel_cadus	uint16	1	= 0–650	The total number of flywheel CADUs/VCDUs in this ETM+ major frame.
bit_slip_cadus	uint16	1	= 0–650	The total number of CADUs/ VCDUs detected with bit slip errors in this ETM+ major frame.
r-s_err_vcdus	uint16	1	= 0–650	The number of VCDUs with Reed-Solomon error used in building this ETM+ major frame.
bch_corrected_ vcdus	uint16	1	= 0–650	The total number of VCDUs, containing corrected BCH errors in this major frame.
bch_uncorrected_ vcdus	uint16	1	= 0–650	The total number of VCDUs containing uncorrected BCH errors in this major frame.
filled_scan_flag	uint8	1	0 = No fill data used in this scan 1 = Entirely filled scan 2 = Partially filled scan	This flag indicates whether any predetermined fill data were used to build this ETM+ scan (major frame). There are nominal 7,423 minor frames in a scan.
minf_filled	uint16	1	= 0–7500	The total number of filled minor frames in this ETM+ major frame. There are nominal 7,423 minor frames in a scan.

5.3.3.2 PCD Vdata

A PCD major frame is generated every 4.096 spacecraft seconds. Each record in the PCD Vdata represents a major frame and is uniquely identified by its associated spacecraft time, which is extracted or computed from raw PCD. The Vdata format for the PCD is neutral with respect to format 1 and format 2 data. The LPS should produce mirror copies of the PCD file for both formats if they are received with the same PCD minor frame words with the same errors.

LPS puts out a fill value in the PCD data records when fields cannot be accurately constructed, computed, interpolated, or flywheeled from the available unpacked PCD words and minor frames in a PCD major frame. The LPS uses a default value of -1 for all signed number types, maximum values for unsigned number types, and the dollar sign ($) for character data types. The fields cycle_count and Majf_count are always calculated and thus never filled.

Table 5–3 lists the contents of the PCD Vdatas for either format 1 or 2. All data in the table are presented in their respective engineering units except for the ETM+ thermistor temperatures.

Coefficients found in the CPF are required for this conversion. Additional details for all table entries can be found in the *Landsat 7 System Data Format Control Book (DFCB), Volume IV—Wideband Data* (see Section 1.4, Applicable Document 2).

Table 5–3. PCD Vdata—Format 1 or 2 (1 of 10)

Vdata Name: "L7XsssfnYYDOYHHuuv.PCD"				
Vdata Class: LPS_PCD				
Interlace Type: FULL_INTERLACE				
Bytes Per Logical Record: 26,512				
Number of Records: One record per PCD major frame (4.096 spacecraft second)				
Field Name	**Number Type**	**Count**	**Description**	**Remarks**
cycle_count	uint8	1	PCD cycle number (00–99) There are approximately 52 PCD cycles in a 14-minute subinterval.	The PCD cycle number associated with PCD major frame reported in this record of the PCD file. A PCD cycle consists of a set of four consecutive PCD major frames: (0), (1), (2), and (3). This number is incremented by one for each PCD major frame.
majf_count	uint8	1	Major frame counter (001–255) The maximum number of PCD major frames in a 14-minute subinterval is 206.	The major frame counter value of the PCD major frame reported in this record of the subinterval PCD file. The PCD major frame number is incremented by one for each new PCD major frame added to this file.
majf_id	uint8	1	PCD major frame ID (0–3) Fill value = 255	PCD major frame (0) is identified by the presence of spacecraft ID and timecode information. Other PCD major frames are identified by their ID numbers (1–3).
majf_time	float64	1	PCD major frame time in GMT integer and fractional seconds since January 1, 1993, rounded to 7 decimal places. Fill value = –10	This time is the PCD major frame time (majf_timecode; see next entry) converted by LPS to seconds since January 1, 1993.
scan_timecode	char8	25	Scan line time of the form YYYY:ddd:hh:mm:ss.ttttttt where YYYY = 4-digit Julian year ddd = Julian day (001–366) hh = Hours (00–23) ss = Seconds (00–59) ttttttt = Fractional seconds (0–9999375, where the clock cycle is 1/16 ms) Fill value = $$$$....	For PCD major frame (0), the spacecraft time is extracted from PCD major frame (0) of a PCD cycle. For PCD major frames 1–3, the spacecraft timecode is interpolated using the time received for PCD major frame (0) of the associated PCD cycle. Time is expressed using the GMT standard. Fill value occurs at the beginning of the PCD file when there has not yet been a valid major frame (0) or there is a missing cycle.

Table 5–3. PCD Vdata—Format 1 or 2 (2 of 10)

Field Name	Number Type	Count	Description	Remarks
band_states	char8	8	Indicates ETM+ bands on/off states for format 1 and format 2 data. = 12345678 for all bands "ON" state in format 1 and format 2 data. A "–" indicates an off state or a missing band (e.g., "123–5678" means band 4 is off or missing). Fill value = $$$$$$$$	This information is extracted from the third PCD major frame, minor frame 32, word 72, bits 0–6 and major frame 2, minor frame 35, word 72, bit 0.
fac_flag	uint8	1	Full aperture calibration door flag: = 0 indicates no activity = 1 indicates calibration door activity (open and/or imaging) Fill value = 255	ETM+ calibration activity status. This status is interpolated from "serial word P" of the third PCD major frame, minor frame 84, word 72, bits 2 and 3.
PCD Major Frame Quality and Accounting Data ***Except for majf_flag and timecode_flag, which have fill or missing indicators, the value 0 is used for an entirely filled major frame.***				
unpacked_pcd_words	uint32	1	= 0–147,497 unpacked PCD words received for this major frame	Count of unpacked PCD words received for this PCD major frame.
unpacked_words_missing	uint32	1	= 0–147,497 unpacked PCD words missing for this major frame	Count of unpacked PCD words identified as missing due to missing VCDUs. Some received PCD major frames may contain LPS filled data.
vote_errors	uint16	1	= 0–16384 packed words in a PCD major frame	Count of (packed) PCD major frame words found to contain voting errors during packing a PCD word/minor frame. Some PCD major frame words may contain erroneous or LPS filled data.
minf_sync_errors	uint8	1	= 0–128 (minor frames per major frame)	Count of PCD minor frames received with sync errors in this major frame. Some PCD words may be lost and filled due to minor frame sync errors.
minf_id_errors	uint8	1	= 0–128 (minor frames per major frame)	Count of PCD minor frames received with incorrect minor frame IDs (counter values). Corrected IDs are filled in.
minf_filled	uint8	1	= 0–128 (minor frames per major frame)	Count of PCD minor frames found with erroneous data in PCD words and filled by LPS with a known value.

Table 5–3. PCD Vdata—Format 1 or 2 (3 of 10)

Field Name	Number Type	Count	Description	Remarks
majf_flag	uint8	1	PCD major frame flag where 0 = Valid major frame ID 1= Incorrect major frame ID 2 = Missing major frame ID; used for major frames (1), (2), and (3) only. If in error, the PCD major frame ID is corrected by LPS.	Indicates the quality of the PCD major frame ID found in word 72, minor frames 96–103 of PCD major frames (1), (2), and (3). PCD major frame (0) contains the timecode flag (see below).
timecode_flag	uint8	1	Valid PCD timecode flag, where 0 = Valid timecode and spacecraft ID 1 = Computed timecode 2 = Corrected spacecraft ID 3 = Flags 1 and 2 combined 4 = Fill value for timecode 5 = Fill value for timecode and spacecraft ID	Indicates the quality of the spacecraft ID and timecode data contained in word 72, minor frames 96–103, of PCD major frames(0). For PCD major frames (1)– (3), the timecode flag is also interpolated/ derived from the timecode flag used for major frame (0).
PCD Major Frame Clock, Temperature, Ephemeris, and Attitude Data				
spacecraft_id	char8	1	spacecraft_id = 7	The Landsat 7 spacecraft ID is determined from bytes 0–3 of PCD timecode word 96 located in major frame (0) of each PCD cycle. For the remaining three major frames in a PCD cycle, this spacecraft ID is copied for each major frame. The spacecraft ID is also forced to "7" when an erroneous ID is read or the spacecraft ID is missing. The spacecraft ID error is noted in the s/c_id_pcd field.
The following four parameters are used to correct the spacecraft time, reported in the PCD and video, for clock drift to within 15 ms of universal time coordinated (UTC) using the following formulas. $\Delta t = Tsc - sv\_clk\_last\_u/d\_time$ $Tc = Tsc + C0 + C1\ \Delta t + .5\ C2\ (\Delta t\ \Delta t)$ where Tc is correct time, Tsc is uncorrected time, Δt is spacecraft clock time relative to last update.				
sv_clk_last_u/d_ time	float64	1	sv_clk_last_u/d_time = 0–31,622,400 seconds from midnight of the first day of the current year. Fill value = –1.0	The time of the last space vehicle clock update is inserted in the PCD stream by the Mission Operations Center (MOC) once per day during ETM+ nonimage periods.
time_drift_bias_c0	int16	1	Spacecraft time drift bias (C0) = –15 to +15 ms Fill value = 7FFF	Clock correction bias term—can be used to minimize the clock error over some span of time; may be set to zero if not needed.

Table 5–3. PCD Vdata—Format 1 or 2 (4 of 10)

Field Name	Number Type	Count	Description	Remarks
time_drift_rate_c1	int16	1	Spacecraft clock drift rate (C1) = +/– ms/day Fill value = 7FFF	Clock correction first order coefficient (drift rate).
time_drift_acceln_c2	int16	1	Spacecraft clock drift acceleration (C2) = +/– ms/day^2 Fill value = 7FFF	Clock correction second order coefficient (drift acceleration); may be set to zero if not needed.
ETM+ Telemetry Sampled @4.096 Seconds Rate The following ETM+ telemetry is sampled every 4.096 seconds and inserted into the next PCD major frame. Major frames with missing or erroneous values are filled with ones (FF in hexadecimal for uint8 and FFFF for uint16).				
black_body_temp_iso	uint8	1	Black body temperature (Isolated)	
cfpa_heater_current	uint8	1	Cold focal plane assembly (CFPA) heater current	
cal__shutr_flag_temp	uint8	1	Calibration shutter flag temperature	
b/u_shutr_flag_temp	uint8	1	Backup shutter flag temperature	
black_body_temp_con	uint8	1	Black body temperature (control)	
baffle_temp_heater	uint8	1	Baffle temperature (heater)	
cfpa_control_temp	uint8	1	CFPA control temperature	
pdf_a/d_ground_ref	uint16	1	PDF A/D ground reference	
ETM+ Telemetry Sampled @16.384 Seconds Rate The following PCD values are repeated for each PCD major frame. Major frames with missing or erroneous values are filled with ones (FF in hexadecimal).The following PCD values should be copied in the same format as found in their respective PCD words/minor frames in a PCD major frame.				
serial_words_a_s	uint8	18	a,b,c,d,e,f,g,h,i,j,k,l,m,n,p,q,r,s	Serial Word "A" — Bits PS 2 Therm Shutdown Enabled 0 PS 1 Therm Shutdown Enabled 1 SMA +Z Heater Controller ON 2 SMA –Z Heater Controller ON 3 Spare 4 Shutter Link Switch A Closed 5 Shutter Link Switch A Closed 6 Shutter Link Switch A Closed 7 Serial Word "B" — Bits Band 1 ON 0 Band 2 ON 1 Band 3 ON 2 Band 4 ON 3 Band 5 ON 4 Band 6/mir ON 5 Band 7 ON 6 Cold Stage Telemetry ON 7

Table 5–3. PCD Vdata—Format 1 or 2 (5 of 10)

Field Name	Number Type	Count	Description	Remarks
serial_words_a_s (continued)				Serial Word "C" — Bits Cooler Door (CD) Closed 0 CD Outgas Position 1 CD Full Open 2 CD Magnet ON 3 CD Motor Drive ON 4 CD Link Switch A Closed 5 CD Link Switch A Closed 6 CD Link Switch A Closed 7 Serial Word "D" — Bits IC Lamp 1 ON 0 IC Lamp 2 ON 1 Spares 2,5,6,7 IC Lamp 1 Backup ON 3 IC Lamp 2 Backup ON 4 Serial Word "E" — Bits Band P ON 0 Spare 1 Blackbody Heater Controller ON 2 Blackbody T2 ON 3 Blackbody T3 ON 4 Blackbody Backup ON 5 SME 1 ON 6 SME 2 ON 7 Serial Word "F" — Bits Baffle Heater Controller ON 0 Baffle Heater Backup ON 1 Spare 2 Spare 3 Spare 4 Spare 5 Spare 6 Spare 7 Serial Word "G" — Bits Scan Line Corrector 1 ON 0 Scan Line Corrector 2 ON 1 Calibration Shutter ON 2 Calibration Shutter Phase Error 3 Calibration Shutter Amp. Error 4 Backup Shutter ON 5 Backup Shutter Phase Error 6 Backup Shutter Amp. Error 7 Serial Word "H" — Bits Cold Stage Heater Cont. ON 0 Cld Stge Outgas Heat. Cont. ON 1 Int. Stage Heater Controller ON 2 Int. Stage Heater Enabled 3 CFPA Heater Controller ON 4 CFPA T2 Relay ON 5 CFPA T3 Relay ON 6 CFPA Telemetry ON 7

Table 5–3. PCD Vdata—Format 1 or 2 (6 of 10)

Field Name	Number Type	Count	Description	Remarks
serial_words_a_s (continued)				Serial Word "I" — Bits DC Restore Normal 0 Frame DC Restore Selected 1 Telemetry Scaling ON 2 SMA +Z Heater Enabled 3 SMA –Z Heater Enabled 4 Spare 5 SME 1 Select SAM 6 Spare Opto 7 Serial Word "J" — Bits AEM Mtpx 1 Bnd 1 Gain State 0 AEM Mtpx 1 Bnd 2 Gain State 1 AEM Mtpx 1 Bnd 3 Gain State 2 AEM Mtpx 1 Bnd 4 Gain State 3 AEM Mtpx 1 Bnd 5 Gain State 4 AEM Mtpx 1 Bnd 6 PRI G State 5 AEM Mtpx 1 Band 7 Gain State 6 AEM Mtpx 1 Band P Gain State 7 Serial Word "K" — Bits AEM Mtpx 2 Bnd 1 Gain State 0 AEM Mtpx 2 Bnd 2 Gain State 1 AEM Mtpx 2 Bnd 3 Gain State 2 AEM Mtpx 2 Bnd 4 Gain State 3 AEM Mtpx 2 Bnd 5 Gain State 4 AEM Mtpx 2 Bnd 6 PRI G State 5 AEM Mtpx 2 Band 7 Gain State 6 AEM Mtpx 2 Band P Gain State 7 Serial Word "L" — Bits Cooler Door Dir. (1 = Open) 0 Cooler Door Move Enable 1 FAC Failsafe Stat Mot Pow ON 2 FAC Primary Stat Mot Pow ON 3 FAC Primary Motor Power ON 4 FAC Failsafe Motor Power ON 5 FAC Primary Contr. Direction 6 FAC Failsafe Contr. Direction 7 Serial Word "M" — Bits Mux 1/2 Anlg Power Selected 0 Mux 1/2 Digtl Power Selected 1 Spare 2 Spare 3 FAC Prim Contr Sngl Stp Sizes 4 FAC Flsfe Contr Sngl Stp Sizes 5 FAC Primary Contr Power ON 6 FAC Failsafe Contr Power ON 7

Table 5–3. PCD Vdata—Format 1 or 2 (7 of 10)

Field Name	Number Type	Count	Description	Remarks
serial_words_a_s (continued)				Serial Word "N" — Bits AEM Multiplexer 1 ON 0 AEM Multiplexer 2 ON 1 AEM Mtpx 1 MDE ON Status 2 AEM Mtpx 2 MDE ON Status 3 AEM Mtpx 1 B6 RDT Gain St 4 AEM Mtpx 2 B6 RDT Gain St 5 AEM Mtpx 1 Data Priority Sel 6 AEM Mtpx 2 Data Priority Sel 7 Serial Word "P" — Bits FAC Stow Position Switch PRI 0 FAC Stow Position Switch RDT 1 AEM Cal Position Switch PRI 2 AEM Cal Position Switch RDT 3 AEM Cal/Stw Mv ON Stat PRI 4 AEM Cal/Stw Mv ON Stat RDT 5 AEM Mtpx 1 Data Priority Sel 6 AEM Mtpx 2 Data Priority Sel 7 Serial Word "Q" — Bits FAC Pull-Pin (PP) Heater 1 ON 0 FAC PP Heater 2 ON 1 FAC PP Heat Pwr, En PRI 2 FAC PP Heater Power 3 FAC PP Retrct Pos Swtch PRI 4 FAC PP Retrct Pos Swtch RDT 5 FAC PP Fully Ret Pos Swt PRI 6 FAC PP Fully Ret Pos Swt RDT 7 Serial Word "R" — Bits FAC Prim CW Rot Swtch Stat 0 FAC Prim CCW Rot Swtch Stat 1 FAC Red CW Rot Swtch Stat 2 FAC Red CCW Rot Swtch Stat 3 Spare 4 Spare 5 Spare 6 Spare 7 Serial Word "S" — Bits Command Reject, Enable 1 P 0 Command Reject, Enable 2 P 1 Command Reject, Enable 3 P 2 Command Reject, Enable 4 P 3 Command Reject, Enable 1 R 4 Command Reject, Enable 2 R 5 Command Reject, Enable 3 R 6 Command Reject, Enable 4 R 7
mux1_elec_temp	uint8	1	Mux 1 electronics temperature	See group comment above.
mux1_ps_ temp	uint8	1	Mux 1 power supply temperature	See group comment above.
mux2_elec_temp	uint8	1	Mux 2 electronics temperature	See group comment above.

Table 5–3. PCD Vdata—Format 1 or 2 (8 of 10)

Field Name	Number Type	Count	Description	Remarks
mux2_ps_temp	uint8	1	Mux 2 power supply temperature	See group comment above.
acs_cpu_mode	uint8	1	Attitude Control System (ACS) CPU mode	See group comment above.
etm_tlm_mnf_16_30	uint8	15	ETM telemetry MF(2), mfs (16–30)	See group comment above.
etm_tlm_mnf_40_49	uint8	10	ETM telemetry MF(2) mfs (40–49)	See group comment above.
etm+_on_time	float64	1	Time ETM+ was last on: etm_on_time = 0–31,622,400 seconds from midnight of the first day of the current year. Reported for each PCD major frame (0) record. If a PCD major frame (1, 2, or 3) does not contain the required PCD value, use –1.0 as the fill value.	Reported as an HDF double precision floating point number to accommodate the 48-bit extended precision floating point value/ sample received in major frame (0) of a PCD cycle.
etm+_off_time	float64	1	Time ETM+ was last off: See above for related description.	See above.
Ephemeris Data The ephemeris data, consisting of the position and velocity components, are available on a PCD major frame basis.				
ephem_position_xyz	float64	3	x,y,z position range: +/– 8.3886 x 10^6 meters Fill value = 10^7	The coordinate system is the J2000 and is defined in the Program Coordinates System Standard.
ephem_velocity_xyz	float64	3	x,y,z velocity range: +/– 8.0 meters/ms Fill value = 10	
Attitude Estimate The spacecraft calculates an estimate of the attitude represented as Euler parameters. Components 1–3 define the eigen-axis of rotation in Earth Center Inertial (ECI) coordinates, and component 4 defines the rotation about that axis				
attitude_est_epa1234	float64	4	epa1, epa2, epa3, epa4 Fill value = 2	epa1, epa2, epa3 are components 1–3. epa4 is component 4.
Gyro (Inertial Measurement Unit (IMU) Axes) Data Note: The following IMU axes (x, y, z) readings are repeated 64 times in each major frame. The IMU axes values are in arc-seconds of angular motion. A total of 256 readings (samples) are collected for each PCD cycle. The Gyro data order is as follows: – all 64 roll values (Roll-1, Roll-2...) – all 64 pitch values (Pitch-1, Pitch-2...) – all 64 yaw values (Yaw-1, Yaw-2...) Each IMU axes counter value is first constructed by concatenating the 3 bytes for each axis (e.g., x1, x2, x3) and then converting to arc-seconds. For converting the IMU counter values to engineering units, each increment or decrement in the 24-bit counter value of an IMU axis represent a 0.061 arc-second change. Fill values are MAXFLOAT.				

Table 5–3. PCD Vdata—Format 1 or 2 (9 of 10)

Field Name	Number Type	Count	Description	Remarks
gyro-select_data	char8	1	= "A" for gyro A selected, or = "B" for gyro B selected, or = "–" to indicate a gyro select error (decoding error) (TBR). A gyro selection is error free when all three X, Y, and Z axes associated with a selected gyro A or B, are true (1s for gyro A and 0s for gyro B). Fill value = $	Bits 0–2 of minor frame 34 in subcom word 72 of PCD major frame 0 identifies the Landsat 7 selected gyro, A or B. Bits 3–7 are ignored.
imu_roll_x00_x63	float64	64	= – 511705.088 to + 511705.027 arc-seconds for components x00–x63 in the PCD major frame.	See above.
imu_pitch_y00_y63	float64	64	= – 511705.088 to + 511705.027 arc-seconds for components y00–y63 in the PCD major frame.	See above.
imu_yaw_z00_z63	float64	64	= – 511705.088 to + 511705.027 arc-seconds for components z00–z63 in the PCD major frame.	See above.
Gyro Drift Data The gyro drift data are reported once per PCD cycle in major frame (0) only. The calculation is made at the PCD cycle time code minus 8.192 seconds in the ACS reference axis coordinate system.				
gyro_drift_theta-xyz	float64	3	x, y, z gyro drift The units of gyro drift (rate) data for each axis are in radians/512 ms. Fill value = –1.0	The least significant bit weight of the theta value is adjusted to 2^{-47} before converting to engineering units.
Angular Displacement Sensor Data (ADS) Note: The minor frame IDs are reported serially for each major frame. The 16 sets of ADS x, y, z values are reported as a distinct entry for each of the 128 minor frames in a PCD major frame. All ADS x, y, z measurements are converted to microradians and reported in ascending order of their source words and minor frames in a PCD major frame. All data are reported with single floating point precision. A total of 16 ADS measurements, each consisting of the x, y and z components, are received in a PCD minor frame. Fill value for all, including mnfm_ids_000_127, is 255.				
mnfm_ids_000_127	uint8	128	Minor frame counter or ID: 000–127	The PCD minor frame counter value/ID from word location 65 of each minor frame. There are 128 (IDs: 000–127) minor frames in a PCD major frame.

Table 5–3. PCD Vdata—Format 1 or 2 (10 of 10)

Field Name	Number Type	Count	Description	Remarks
ads_xyz16_mnfm_000	float32	48	ADS measurement x01, y01, z01 through x16,y16,z16 received in minor frame 0	
ads_xyz16_mnfm_001	float32	48	ADS measurement x01, y01, z01 through x16,y16,z16 received in minor frame 1	
• • •	• • •	• • •	ADS measurements as above for minor frames 2 through 126	
ads_xyz16_mnfm_127	float32	48	ADS measurement x01, y01, z01 through x16,y16,z16 received in minor frame 127	
ADS Temperatures Note: The ADS x, y, z, and A/D electronic temperature values are reported on a major frame basis (i.e., every 4.096 seconds). All temperatures are reported in degrees Centigrade.				
ads_temp_xyz+a/d	float32	4	See above. Includes temperature values for components: x, y, z and elec_a/d. Fill value = 255	See above.
PCD Quality and Accounting Data The following PCD quality data are LPS-produced and appended to each major frame record of the PCD file.				
s/c_id_err_pcd	char8	1	Spacecraft ID error in PCD: s/c_id_err_pcd = "n" for no errors "y" for errors detected in the spacecraft ID field	The error flag is true whenever the spacecraft ID is not equal to "7" and is corrected to "7".
att_data_quality	char8	1	Attitude Data Point Quality: att_data_ quality = "g" for good data "r" for rejected data "m" for missing data	Determined and produced by LPS for each PCD major frame. "r" indicates that the attitude data failed range check. "m" indicates missing attitude data replaced with fill data.
ephem_data_quality	char8	1	Ephemeris Data Point Quality: ephem_data_quality = "g" for good data "r" for rejected data "m" for missing data	Determined and produced by LPS for each PCD major frame. "r" indicates ephemeris data failed range check. "m" indicates missing ephemeris data replaced with fill data.

5.3.3.3 Scan Line Offsets Vdata

The scan line offset tables provide the amount of zero-fill before actual scene and calibration data and after actual scene data on a data-line-by-data-line basis. Offsets result from the detector arrangement on the two focal planes, a scan line length that can vary from nominal, and the

decision to include all data in the 0R product. There is one scan line offset Vdata per product band or band segment (i.e., band 8). The number of Vdata records or entries is equal to the number of data lines in the corresponding band or band segment file.

Two external elements or files, one for each format, are used to store the scan line offset Vdatas. They are ordered or stacked in a band sequential format, which means all band 1 records are followed by band 2, followed by band 3 and so on. Multisegment band 8 Vdatas are sequentially ordered by ascending data line number.

As with other product tables, the scan line offset Vdatas follow similar naming conventions. However, the extensions vary so to associate each Vdata with its particular band. The scan line offset names are as follows:

Format 1	Format 2
Band 1 – "L7XsssfnYYDOYHHuuv.O10"	Band 6 – "L7XsssfnYYDOYHHuuv.O60"
Band 2 – "L7XsssfnYYDOYHHuuv.O20"	Band 7 – "L7XsssfnYYDOYHHuuv.O70"
Band 3 – "L7XsssfnYYDOYHHuuv.O30"	Band 8 – "L7XsssfnYYDOYHHuuv.O81"
Band 4 – "L7XsssfnYYDOYHHuuv.O40"	Band 8 – "L7XsssfnYYDOYHHuuv.O82"*
Band 5 – "L7XsssfnYYDOYHHuuv.O50"	Band 8 – "L7XsssfnYYDOYHHuuv.O83"*
Band 6 – "L7XsssfnYYDOYHHuuv.O60"	

* Used for multisegment band 8 products

Table 5–4 lists the contents of either the format 1 or 2 scan line offsets.

Table 5–4. Scan Line Offsets Vdata (1 of 2)

Vdata Name: "L7XsssfnYYDOYHHuuv.ONN"
Vdata Class: LPS_SLO
Interlace Type: FULL_INTERLACE
Bytes Per Logical Record: 44
Number of Records: One record per data line for the corresponding band file.

Field Name	Number Type	Count	Description	Remarks
scan_timecode	char8	25	Scan line time of the form 'YYYY:ddd:hh:mm:ss.tttttt' where YYYY = 4-digit Julian year ddd = Day (01 through 366) hh = Hours (00 through 23) mm = Minutes (00 through 59) ss = Seconds (00 through 59) tttttt = Fractional seconds (0–9999375, where the clock cycle is 1/16 ms)	The ETM+ scan start time extracted from the timecode minor frames of the ETM+ major frame data reported in this record. A computed scan start time is provided if a valid time is not available from the ETM+ time code minor frames. The scan time code is referenced to GMT.
scan_time	float64	1	The ETM+ scan time in decimal notation seconds since midnight on January 1, 1993, rounded to 7 decimal places.	The scan_time is obtained by converting the scan_timecode (last entry) to seconds. This is also referenced to GMT.

Table 5–4. Scan Line Offsets Vdata (2 of 2)

Field Name	Number Type	Count	Description	Remarks
scan_no	uint16	1	scan_no = 1–11,725 The maximum scan count is based on a subinterval duration of 14 minutes for 35 scenes, each consisting of 335 nonoverlapping scans.	A sequence counter for ETM+ scans (major frames) contained in a subinterval. The ETM+ scan counter is incremented by one for each new scan, real or flywheeled, added to the subinterval file. This counter is referenced relative to the original subinterval, not the product ordered.
scan_data_line_no	uint32	1	scan_data_line_no = SSSSSS where SSSSSS = 1–187,600 for bands 1–5 and 7 = 1–93,800 for band 6 = 1–375,200 for band 8 Note: The band 8 scan data line count is not reset between segments (1–3).	The scan line counter is incremented for each detector data line added to the product band file. There are 16 scan data lines each for bands 1–5 and 7, 8 for band 6, and 32 for band 8 in each ETM+ scan. The maximum line counts are shown for a 14-minute subinterval (35 scenes).
detector_id	uint8	1	where the detector_id is in the range: = 1–16 for bands 1–5 and 7 = 1–8 detectors for band 6 = 1–32 for band 8	Each scan line in an image file consists of samples from a single detector of a single band. Each detector, chosen in a descending ID order, is used once during each scan for generating a scan line.
scan_data_line_ offset_rhs	int16	1	= 0–280 bytes for bands 1–5 and 7 = 0–140 bytes for bands 6L (format 1) and 6H (format 2) = 0–560 bytes for band 8 The scan line data may be shifted to right in the band data buffer after an integer-pixel alignment.	The scan line data are shifted to the right in a larger buffer to accommodate integer pixel alignment without data loss. After integer-pixel alignment, this field indicates the trailing zero fill buffer for each data line. This offset can accommodate an enlarged active scan line length from attitudinal gyrations and ETM+ bumper wear.
scan_data_line_ offset_lhs	int16	1	= 0–280 bytes for bands 1–5 and 7 = 0–140 for band 6 = 0–560 for band 8	Note: The left-hand-side offset is not as significant as the right-hand-side margin. It can accommodate scan line length growths due to ETM+ scanner bumper wear.

5.3.3.4 Geolocation Index Vdata

Table 5–5 lists the contents of the geolocation index Vdata. The data line numbers are referenced relative to the subinterval from which the product came and represent actual overlapping WRS scene corners.

Table 5–5. Geolocation Index Vdata

Vdata Name: "L7XsssfnYYDOYHHuuv.GEO"			
Vdata Class: Index			
Interlace Type: FULL_INTERLACE			
Bytes Per Logical Record: 57			
Number of Records: One record per WRS scene in the product			
Field Name	**Number Type**	**Count**	**Description**
UlLon	float32	1	Scene longitude – upper left corner
UlLat	float32	1	Scene latitude – upper left corner
UrLon	float32	1	Scene longitude – upper right corner
UrLat	float32	1	Scene latitude – upper right corner
LlLon	float32	1	Scene longitude – lower left corner
LlLat	float32	1	Scene latitude – lower left corner
LrLon	float32	1	Scene longitude – lower right corner
LrLat	float32	1	Scene latitude – lower right corner
FirstLine_15m	int32	1	Beginning scene line number – 15m
LastLIne_15m	int32	1	Ending scene data line number – 15m
FirstLine_30m	int32	1	Beginning scene line number – 30m
LastLine_30m	int32	1	Ending scene line number – 30m
FirstLine_60m	int32	1	Beginning scene line number – 60m
LastLIne_60m	int32	1	Ending scene line number – 60m
FullScene	char8	1	Full scene indicator flag (Y or N)

5.3.4 Metadata Definitions

Three metadata files accompany a 0R product. They are structured using the ODL syntax as ASCII text blocks. Two of the files are created by LPS and describe the subinterval used to create a product. The third file is created by ECS and describes the contents of the product actually ordered.

5.3.4.1 LPS Metadata

The two LPS metadata files describe format 1 and format 2. They contain metadata for the subinterval as well as individual scenes. The subinterval metadata contain reference information on the raw wideband data source (e.g., an LGS X-band channel), the LPS resources (equipment strings) used in Level 0R processing, and identification information on the Level 0R data files produced for the archive. The scene metadata provide details on each WRS scene identified in a subinterval during Level 0R processing. Each scene is a logically separated metadata group containing identification information such as scene center and corner coordinates, cloud cover

scores, and quality and accounting information on the image data and PCD associated with the scene. Up to 35 full scene groups may occur for a 14-minute maximum Landsat 7 contact period.

The LPS metadata file for both formats is defined in Table 5–6. The format 1 file contains subinterval and scene metadata for bands 1 through 6. Likewise, the format 2 file contains subinterval and scene metadata for bands 6 through 8. The browse file names and the cloud cover scores are provided in the format 1 metadata file only. The two LPS files undergo no content change during 0R product generation but are transformed from standalone ODL files to HDF external elements using the Vdata interface. The actual ODL files are identical but now HDF addresses and offsets are placed in the HDF directory file common to all product components. This allows metadata access using HDF tools if desired.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (1 of 23)

Vdata Name: "L7XsssfnYYDOYHHuuv.MTA"			
Vdata Class: LPS_Metadata			
Interlace Type: FULL_INTERLACE			
Bytes Per Logical Record: 65536			
Number of Records: One record.			
Field Name: Metadata_Format_1 or Metadata_Format_2			
Data Type: Char8 – Count: 65536			
Parameter Name	**Size (ASCII bytes)**	**Value, Format, Range, and Units**	**Parameter Description/Remarks**
GROUP	13	= METADATA_FILE	Beginning of the first level ODL group. It indicates the start of the LPS Metadata File Level Group records for an ETM+ format 1 or format 2 subinterval.
GROUP	18	= METADATA_FILE_INFO	Beginning of the second level ODL group. It indicates the start of the LPS Metadata File Information Group records.
FILE_NAME	22	= "L7XsssfnYYDOYHHuuv.xxx" where xxx = "MTA" for the metadata file.	Complete details on the LPS file naming convention are specified in Section 5.3.1
FILE_CREATION_DATE_TIME	20	= YYYY-MM-DDThh:mm:ssZ whereYYYY = 4-digit Julian year (e.g.,1998 and 2001) MM = Month number of a Julian year (01–12 for January to December) DD = Day of a Julian month (01–31) T indicates the start of time information in the ODL time code format hh = Hours (00–23) mm = Minutes (00–59) ss = Seconds (00–59) Z indicates "Zulu" time (same as GMT)	The LPS system date and time when the metadata file for a Level 0R file set was created. For ease of human readability, this date and time information is presented in the ODL ASCII format. The time is expressed as Universal Coordinated Time (also known as Greenwich Mean Time (GMT)). Insertion of additional characters "T" and "Z" is required to meet the ODL ASCII time format.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (2 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
FILE_VERSION_NO	1	= 0–9, where FILE_VERSION_NO = 0 indicates "not a reprocessed file" FILE_VERSION_NO = 1–9 indicates the file reprocess count. The 1-digit LPS file version no. is also used in the FILE_NAME.	Reprocessing indicator to distinguish this file from the metadata file generated earlier for the same subinterval and provided to the EDC DAAC. The reprocessing information is entered/ supplied by an operator during setup of the Level 0R processing operations.
STATION_ID	3	= SSS, where SSS indicates a 3-character ground station code. For LPS, SSS = "EDC" for station contacts received directly at EDC. For data received from other stations, SSS = “AGS” for Fairbanks, Alaska, and “SGS” for Svalbard, Norway. If data are received on tape from an IGS station, then the IGS station ID is used. See the Landsat 7 to IGS ICD for the full set of IGS stations.	This parameter identifies the Landsat 7 ground station that received the raw data from Landsat 7. This parameter distinguishes metadata and their associated Level 0R files processed from files received directly at EDC from data originating at other ground stations.
SOFTWARE_VERSION_NO	5	= “X.Y.Z”, where X is the major release number. Y is the minor release number. Z is the patch (or engineering) release number. X, Y, and Z are all numeric numbers.	Version number of the software installed on the LPS string when metadata and associated Level 0R files were generated.
L7_CPF_NAME	25	= “L7CPFyyyymmdd–yyyymmdd.nn”, where yyyymmdd = effective_date_begin and effective_date_end, respectively nn= Incrementing version number for within a quarter (00–99)	The name of the Landsat 7 CPF received from IAS and used in generating the Level 0R files identified in this metadata file. Note: 00 is valid only for prelaunch CPF.
END_GROUP	18	= METADATA_FILE_INFO	End of the second level ODL group. It indicates the end of the LPS Metadata File Information Group records.
GROUP	26	= SUBINTERVAL_METADATA_ FMT_m where m = 1 for format 1 or 2 for format 2	Beginning of the second level ODL group. It indicates the start of the ETM+ format 1 or format 2 subinterval level metadata group records.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (3 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
SPACECRAFT_ID	8	= "Landsat7"	
SENSOR_ID	4	= "ETM+"	
CONTACT_PERIOD_ START_TIME	18	YYYY-DOYTHH:MM:SSZ where YYYY = 4-digit Julian year DOY = Julian day of year (001–366) T indicates start of time information in the ODL ASCII time code format HH = Hour of day (00–23) MM = Minutes (00–59) SS = Seconds (00–59) Z indicates “Zulu” time (same as GMT)	The Julian date and GMT when the capture of a Landsat 7 contact period, associated with this subinterval, was started by the LPS. An uppercase time format indicates time obtained from LPS or a Landsat 7 system. A lowercase time format indicates time obtained from the Landsat 7 spacecraft wideband data (image and/or PCD).
CONTACT_PERIOD_ STOP_TIME	18	YYYY-DOYTHH:MM:SSZ (See CONTACT_PERIOD_ START_TIME, above)	The Julian date and GMT when capture of a contact period, associated with this subinterval, was completed by the LPS.
STARTING_PATH	3	= 001–233 (leading 0s are required)	The WRS path number for the scenes included in this subinterval.
STARTING_ROW	3	= 001–248 (leading 0s are required)	The starting WRS row number for the scene data included in this subinterval.
ENDING_ROW	3	= 001–248 (leading 0s are required)	The ending WRS row number for the scene data included in this subinterval.
SUBINTERVAL_START_ TIME	26	= YYYY-dddThh:mm:ss.ttttttZ where YYYY = 4-digit Julian year ddd = Day (001–366*) T indicates the start of time information in the ODL ASCII time code format hh = Hours (00–23) mm = Minutes (00–59) ss = Seconds (00–59) tttttt = Fractional seconds (0–9999375, where the clock cycle is 1/16 ms) Z indicates “Zulu” time (same as GMT) * For cases when active imaging occurs past the end of a leap year during a single contact period.	The spacecraft time extracted from the timecode minor frames of the first ETM+ major frame of the subinterval reported in this file. A computed start time is provided if the timecode in the first ETM+ major frame is in error. Note: The year information (Capitalized) is appended by LPS to the spacecraft timecode.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (4 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
SUBINTERVAL_STOP_TIME	26	= YYYY-dddThh:mm:ss.ttttttZ where the time format is the same as for SUBINTERVAL_START_TIME, above.	The spacecraft time extracted from the timecode minor frames of the last ETM+ major frame of the subinterval reported in this file. Note: The year information (Capitalized) is appended by LPS to the spacecraft timecode.
TOTAL_ETM_SCANS	1–5	= N–11725 where N is an LPS operator-selectable parameter value for the smallest scene size to be included in a subinterval. The default value of N is 335.	The total number of ETM+ scans reported in this subinterval file. A maximum of 11,725 scans can be received in a 14-minute subinterval (based on a maximum of 35 full scenes, each consisting of at most 335 nonoverlapping scans).
PCD_START_TIME	26	= YYYY-dddThh:mm:ss.ttttttZ where the time format is the same as for SUBINTERVAL_START_TIME, above.	Spacecraft time of the first PCD major frame in the PCD file associated with this subinterval.
PCD_STOP_TIME	26	= YYYY-dddThh:mm:ss.ttttttZ where the time format is the same as for SUBINTERVAL_START_TIME, above.	Spacecraft time of the last PCD major frame in the PCD file associated with this subinterval.
TOTAL_PCD_MAJOR_FRAMES	1–3	= 0–255	The total number of PCD major frames received in the PCD file associated with this subinterval. Approximately 212 major frames can be received by the LPS during a 14-minute subinterval.
SUBINTERVAL_UL_CORNER_LAT	8	= –90.0000 through 90.0000 degrees (with a 4-digit precision) A positive value indicates north latitude. A negative (–) value indicates south latitude.	LPS calculated "actual" latitude value for the upper left corner of the subinterval. A subinterval may start at the first actual scan (not filled) in a partial scene.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (5 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
SUBINTERVAL_UL_ CORNER_LON	9	= –180.0000 through 180.0000 degrees (with a 4-digit precision) A positive value indicates east longitude. A negative (–) value indicates west longitude.	LPS calculated "actual" longitude value for the upper left corner of the subinterval. A subinterval may start at the first actual scan (not filled) in a partial scene.
SUBINTERVAL_UR_ CORNER_LAT	8	= –90.0000 through 90.0000 degrees (with a 4-digit precision) A positive value indicates north latitude. A negative (–) value indicates south latitude.	LPS calculated "actual" latitude value for the upper right corner of the subinterval. A subinterval may start at the first actual scan (not filled) in a partial scene.
SUBINTERVAL_UR_ CORNER_LON	9	= –180.0000 through 180.0000 degrees (with a 4-digit precision) A positive value indicates east longitude. A negative (–) value indicates west longitude.	LPS calculated "actual" longitude value for the upper right corner of the subinterval. A subinterval may start at the first actual scan (not filled) in a partial scene.
SUBINTERVAL_LL_ CORNER_LAT	8	= –90.0000 through 90.0000 degrees (with a 4-digit precision) A positive value indicates north latitude. A negative (–) value indicates south latitude.	LPS calculated "actual" latitude value for the lower left corner of the subinterval. A subinterval may end at the last actual scan (not filled) in a partial scene.
SUBINTERVAL_LL_ CORNER_LON	9	= –180.0000 through 180.0000 degrees (with a 4-digit precision) A positive value indicates east longitude. A negative (–) value indicates west longitude.	LPS calculated "actual" longitude value for the lower left corner of the subinterval. A subinterval may end at the last actual scan (not filled) in a partial scene.
SUBINTERVAL_LR_ CORNER_LAT	8	= –90.0000 through 90.0000 degrees (with a 4-digit precision) A positive value indicates north latitude. A negative (–) value indicates south latitude.	LPS calculated "actual" latitude value for the lower right corner of the subinterval. A subinterval may end at the last actual scan (not filled) in a partial scene.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (6 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
SUBINTERVAL_LR_ CORNER_LON	9	= –180.0000 through 180.0000 degrees (with a 4-digit precision) A positive value indicates east longitude. A negative (–) value indicates west longitude.	LPS calculated "actual" longitude value for the lower right corner of the subinterval. A subinterval may end at the last actual scan (not filled) in a partial scene.
ETM_LAST_ON_TIME	26	= YYYY-dddThh:mm:ss.ttttttZ where the time format is the same as for SUBINTERVAL_START_ TIME above.	See the Landsat 7 DFCB for details on this time.
ETM_LAST_OFF_TIME	26	= YYYY-dddThh:mm:ss.ttttttZ where the time format is the same as for SUBINTERVAL_START_ TIME above.	See description, above, for ETM_LAST_ON_TIME
UT1_CORRECTION	8	= –0.90000–0.90000 seconds This time could be as large as 0.9 seconds in increments of fractions of seconds.	The UTC-UT1 time difference in seconds obtained from the Landsat 7 CPF received from IAS.
BAND1_PRESENT	1	= "Y" indicates that band 1 is present in this subinterval or = "N" indicates that band 1 is not present in this subinterval This field is included in the ETM+ format 1 metadata only.	This is the "Band 1 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 0, where a bit set condition. (=1) indicates "Band 1 ON state." The first error-free PCD major frame (2), found in the subinterval, is used to derive this value.
BAND2_PRESENT	1	(Same as BAND1_PRESENT values and format). This field is included in the ETM+ format 1 metadata only.	This is the "Band 2 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 1, where a bit set condition (=1) indicates "Band 2 ON state." The first error-free PCD major frame (2) is used to derive this value.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (7 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
BAND3_PRESENT	1	(Same as BAND1_PRESENT values and format). This field is included in the ETM+ format 1 metadata only.	This is the "Band 3 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 2, where a bit set condition (=1) indicates "Band 3 ON state." The first error-free PCD major frame (2), found in the subinterval, is used to derive this value.
BAND4_PRESENT	1	(Same as BAND1_PRESENT values and format). This field is included in the ETM+ format 1 metadata only.	This is the "Band 4 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 3, where a bit set condition (=1) indicates "Band 4 ON state." The first error-free PCD major frame (2), found in the subinterval, is used to derive this value.
BAND5_PRESENT	1	(Same as BAND1_PRESENT values and format). This field is included in the ETM+ format 1 metadata only.	This is the "Band 5 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 4, where a bit set condition (=1) indicates "Band 5 ON state." The first error-free PCD major frame (2), found in the subinterval, is used to derive this value.
BAND6_PRESENT	1	(Same as BAND1_PRESENT values and format). This field is included in the ETM+ format 1 or format 2 metadata.	This is the "Band 6/MIR ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 5, where a bit set condition (=1) indicates "Band 6 ON state." The first error-free PCD major frame (2), found in the subinterval, is used to derive this value.
BAND7_PRESENT	1	(Same as BAND1_PRESENT values and format). This field is included in the ETM+ format 2 metadata only.	This is the "Band 7 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 6, where a bit set condition (=1) indicates "Band 7 ON state." The first error-free PCD major frame (2), found in the subinterval, is used to derive this value.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (8 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
BAND8_PRESENT	1	(Same as BAND1_PRESENT values and format). This field is included in the ETM+ format 2 metadata only.	This is the "Band 8 ON" status information obtained from PCD Serial Word "E" (major frame (2), minor frame 35, word 72), bit 0, where a bit set condition (=1) indicates "Band 8 ON state." The first error-free PCD major frame (2), found in the subinterval, is used to derive this value.
TOTAL_WRS_SCENES	1–2	= 0–99 This field is included in ETM+ format 1 and format 2 metadata. Note: The LPS produces this count from the total number of WRS scenes identified in a subinterval. The LPS does not use the absolute difference between STARTING_ROW and ENDING_ROW to compute this +1 count.	This count indicates the total number of WRS scenes identified by LPS in a subinterval. A maximum of 35 full WRS scenes, including partial scenes at the start and/or the end of a subinterval, may be received by LPS in a 14-minute subinterval. This count also indicates the total number of multiband-scene browse files, for full and partial scenes, that may be produced by LPS and reported in the scene metadata.
PARTIAL_WRS_SCENES	1	= 0–2 This field is included in ETM+ format 1 and format 2 metadata.	Indicates the count of partial scenes, if any, at the start and/or at the end of a subinterval.
TOTAL_FILES	1–2	= 10–47 (format 1 with up to 37 multiband browse scene files) or = 6– 9 (format 2 with up to 3 band 8 file segments)	The total number of LPS files included in this subinterval for ETM+ format 1 or format 2. Assuming that a subinterval contains at least one scene, the metadata file will contain the names of a minimum of 10 files (6 band, 1 MSCD, 1 PCD, 1 calibration, and 1 multiband scene browse) for format 1, and 6 files (3 band, 1 MSCD, 1 PCD, and 1 calibration) for format 2, respectively. A maximum of 35 full multiband scene browse files are provided for format 1 subinterval only.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (9 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
BAND1_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.B10” (See Section 5.3.1 for details on the file naming convention. Also note that actual product file names are born from this convention.)	This file name is included in a format 1 metadata file only.
BAND2_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.B20” (See Section 5.3.1 for details.)	This file name is included in a format 1 metadata file only.
BAND3_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.B30” (See Section 5.3.1 for details.)	This file name is included in a format 1 metadata file only.
BAND4_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.B40” (See Section 5.3.1 for details.)	This file name is included in a format 1 metadata file only.
BAND5_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.B50” (See Section 5.3.1 for details.)	This file name is included in a format 1 metadata file only.
BAND6_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.B60” (See Section 5.3.1 for details.)	This file name is included in a format 1 or format 2 metadata file.
BAND7_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.B70” (See Section 5.3.1 for details.)	This file name is included in a format 2 metadata file only.
BAND8_FILE1_NAME	22	= “L7XsssfnYYDOYHHuuv.B81” (See Section 5.3.1 for details.)	This band 8 file segment name is included in a format 2 metadata file only. Up to three band 8 file segments, each up to 2 GB long, are expected in a format 2 subinterval.
BAND8_FILE2_NAME	22	= “L7XsssfnYYDOYHHuuv.B82” (See Section 5.3.1 for details.)	The name of this band 8 file segment, if it exists in a subinterval, is included in a format 2 metadata file only.
BAND8_FILE3_NAME	22	= “L7XsssfnYYDOYHHuuv.B83” (See Section 5.3.1 for details.)	The name of this band 8 file segment, if it exists in a subinterval, is included in a format 2 metadata file only.
MSCD_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.MSD” (See Section 5.3.1 for details.)	Name of the MSCD file associated with this subinterval.
PCD_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.PCD” (See Section 5.3.1 for details.)	Name of the PCD file associated with this subinterval.
CAL_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.CAL” (See Section 5.3.1 for details.)	Name of the calibration file associated with this subinterval.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (10 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
Scene-Level Metadata The following parameters values are repeated for each ETM+ format 1 or format 2 scenes included in a subinterval.			
GROUP	17	= METADATA_SCENE_NN where NN = 01–99 (Up to 35 full scenes are expected in a 14-minute subinterval)	Beginning of the second level ODL group. It indicates the beginning of the ETM+ format 1 or format 2 Scene NN level metadata group records.
GROUP	12	= WRS_SCENE_NN where NN = 01–99	Beginning of the third level ODL group. It indicates the beginning of the ETM+ format 1 or format 2 WRS Scene 1 metadata group records.
Scene-Level Metadata The following parameters values are repeated for each WRS scene included in the subinterval.			
WRS_SCENE_NO	1–2	= 1–99	This is the LPS assigned WRS scene number within a subinterval.
FULL_OR_PARTIAL_ SCENE	1	= F or P where F indicates a full WRS scene or P indicates a partial WRS scene at start or end of a subinterval.	The LPS may receive partial WRS scenes at the start and/or the end of a subinterval.
BROWSE_FILE_NAME	22	= “L7XsssfnYYDOYHHuuv.xxx” for a format 1 subinterval (See Section 5.3.1.) or No browse file names are provided if its a format 2 subinterval. xxx = Rnn where R indicates a multiband scene browse file, and nn = 00–99 indicates the multiband scene browse file number within a subinterval.	The LPS generates multiband scene browse files for ETM+ format 1 (bands 1–6) only. The names of all multiband scene browse files, generated for a format 1 subinterval, are provided with and reported in the format 1 metadata. A maximum of 35 full WRS scenes are possible in a subinterval.
WRS_PATH	3	= 001–233 (Leading zeros are required.)	The WRS path number associated with the scene from PCD scene accounting.
WRS_ROW	3	= 001–248 (Leading zeros are required.)	The WRS row number associated with the scene.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (11 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
SCENE_CENTER_ SCAN_NO	2–5	= 1–11725 (for "actual" scene centers in the subinterval. For a partial scene with less than a half scene length data, the scene center scan number may be outside the actual subinterval band data range. It will point to the nonexistent scan 0 in the band file.	The ETM+ scan number nearest the calculated (actual) center of a WRS scene. A WRS scene scan number within a 14-minute subinterval can be as high as 11,725.
SCENE_CENTER_ SCAN_TIME	26	= YYYY-dddThh:mm:ss.ttttttZ where the time format is the same as for SUBINTERVAL_START_ TIME, above.	The spacecraft time associated with a WRS scene center scan (number).
SCENE_CENTER_LAT	8	= –90.0000 through 90.0000 degrees (with a 4-digit precision) A positive value indicates north latitude. A negative (–) value indicates south latitude.	WRS scene center latitude – LPS calculated coordinate value. The computed "actual" scene centers for full and greater than half a scene length partial scenes are expected to be in proximity of the nominal WRS scene centers. They are always indexed to actual data in the band file. The computed "actual" scene centers for smaller than half a scene length partial scenes are also expected to be in proximity of the nominal WRS scene centers, but outside the actual subinterval band data range. They are indexed to a non-existent scan 0 in the band file.
SCENE_CENTER_LON	9	= –180.0000 through 180.0000 degrees (with a 4-digit precision) A positive value indicates east longitude. A negative (–) value indicates west longitude.	WRS scene center longitude – LPS calculated coordinate value. The computed "actual" scene centers for full and greater than half a scene length partial scenes are expected to be in the proximity of the nominal WRS scene centers. They are always indexed to actual data in the band file.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (12 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
SCENE_CENTER_LON (continued)			The computed "actual" scene centers for less than half a scene length partial scenes are also expected to be in the proximity of nominal WRS scene centers, but outside the actual subinterval band data range. They are indexed to a nonexistent scan 0 in the band file.
HORIZONTAL_DISPLAY_SHIFT	2–5	= – 9999 through 9999 meters A negative (–) value defines a shift of the calculated "true" WRS scene center to the west of the nominal WRS scene center. A positive value defines a shift of the calculated "true" WRS scene center to the east of the nominal WRS scene center.	The horizontal distance between the perpendiculars through the LPS calculated "true" WRS scene center and the nominal (known) WRS scene center on ground. The LPS will maintain a lookup table of nominal WRS scene centers for computing the HORIZONTAL_DISPLAY_SHIFT (HDS) values for WRS scenes.
SCENE_UL_CORNER_LAT	8	= –90.0000 through 90.0000 degrees (with a 4-digit precision) A positive value indicates north latitude. A negative (–) value indicates south latitude.	WRS scene upper left corner "actual" latitude for a full or a partial scene.
SCENE_UL_CORNER_LON	9	= –180.0000 through 180.0000 degrees (with a 4-digit precision) A positive value indicates east longitude. A negative (–) value indicates west longitude.	WRS scene upper left corner "actual" longitude for a full or a partial scene.
SCENE_UR_CORNER_LAT	8	= –90.0000 through 90.0000 degrees (with a 4-digit precision) A positive value indicates north latitude. A negative (–) value indicates south latitude.	WRS scene upper right corner "actual" latitude for a full or a partial scene.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (13 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
SCENE_UR_CORNER_LON	9	= –180.0000 through 180.0000 degrees (with a 4-digit precision) A positive value indicates east longitude. A negative (–) value indicates west longitude.	WRS scene upper right corner "actual" longitude for a full or a partial scene.
SCENE_LL_CORNER_LAT	8	= –90.0000 through 90.0000 degrees (with a 4-digit precision) A positive value indicates north latitude. A negative (–) value indicates south latitude.	WRS scene lower left corner "actual" latitude at for a full or a partial scene.
SCENE_LL_CORNER_LON	9	= –180.0000 through 180.0000 degrees (with a 4-digit precision) A positive value indicates east longitude. A negative (–) value indicates west longitude.	WRS scene lower left corner "actual" longitude at for a full or a partial scene.
SCENE_LR_CORNER_LAT	8	= –90.0000 through 90.0000 degrees (with a 4-digit precision) A positive value indicates north latitude. A negative (–) value indicates south latitude.	WRS scene lower right corner "actual" latitude at for a full or a partial scene.
SCENE_LR_CORNER_LON	9	= –180.0000 through 180.0000 degrees (with a 4-digit precision) A positive value indicates east longitude. A negative (–) value indicates west longitude.	WRS scene lower right corner "actual" longitude at for a full or a partial scene.
SCENE_CCA	1–3	= 0–100 This field is included in the ETM+ format 1 metadata only.	WRS scene cloud cover assessment (CCA) indicates the percent of a WRS scene area covered with clouds. This CCA is an average of the quadrants CCA scores.
UL_QUAD_CCA	1–3	= 0–100 This field is included in the ETM+ format 1 metadata only.	Indicates the percent of the upper left quadrant of the WRS scene area covered with clouds. For partial scenes, the quadrant score is for the quadrant of the actual data and not for what would be for a full WRS scene.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (14 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
UR_QUAD_CCA	1–3	= 0–100 This field is included in the ETM+ format 1 metadata only.	Indicates the percent of the upper right quadrant of the WRS scene area covered with clouds. For partial scenes, the quadrant score is for the quadrant of the actual data and not for what would be for a full WRS scene.
LL_QUAD_CCA	1–3	= 0–100 This field is included in the ETM+ format 1 metadata only.	Indicates the percent of the lower left quadrant of the WRS scene area covered with clouds. For partial scenes, the quadrant score is for the quadrant of the actual data and not for what would be for a full WRS scene
LR_QUAD_CCA	1–3	= 0–100, or This field is included in the ETM+ format 1 metadata only.	Indicates the percent of lower right quadrant of the WRS scene area covered with clouds. For partial scenes, the quadrant score is for the quadrant of the actual data and not for what would be for a full WRS scene
ACCA_ALGORITHM_ID_VER	22	= 22 ASCII characters The algorithm name and version numbers are determined by the Landsat 7 Project. This field is included in the ETM+ format 1 metadata only.	Identifies the automated cloud cover assessment (ACCA) algorithm (name and version number), used by LPS to compute the cloud cover score for this scene.
SUN_AZIMUTH_ANGLE	12	= –180.0000000 through 180.0000000 degrees (with 7-digit precision) A positive value indicates angles to the east or clockwise from north. A negative value (–) indicates angles to the west or counterclockwise from north. (Leading zeros are not required)	The Sun azimuth angle at the "true" WRS scene center (LPS calculated from PCD processing).
SUN_ELEVATION_ANGLE	11	= –90.0000000 through 90.0000000 degrees (with 7-digit precision) A positive value indicates a daytime scene. A negative value (–) indicates a nighttime scene. (Leading zeros are not required)	The Sun elevation angle at the "true" WRS scene center (LPS calculated from PCD processing).

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (15 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
SCENE_BAND1_ PRESENT	1	= "Y" indicates that band 1 is present or = "N" indicates that band 1 is not present = "U" indicates that band 1 presence is unknown This field is included in the ETM+ format 1 metadata only.	This is the "Band 1 ON" state information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 0, where a bit set condition. (=1) indicates "Band 1 ON state" The first error-free PCD major frame (2) associated with the scene is used to derive this value. If no valid PCD major frame falls within the scene's time boundary, then the value for the previous scene will be used. If the previous scene has no valid major frame (e.g., the first partial scene in a subinterval), then the value "U" for unknown is used.
SCENE_BAND2_ PRESENT	1	(Same as SCENE_BAND1_PRESENT values and format). This field is included in the ETM+ format 1 metadata only.	Same as above with exception as noted. This is the "Band 2 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 1, where a bit set condition (=1) indicates "Band 2 ON state."
SCENE_BAND3_ PRESENT	1	(Same as SCENE_BAND1_PRESENT values and format). This field is included in the ETM+ format 1 metadata only.	Same as above with exception as noted. This is the "Band 3 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 2, where a bit set condition (=1) indicates "Band 3 ON state."
SCENE_BAND4_ PRESENT	1	(Same as SCENE_BAND1_PRESENT values and format). This field is included in the ETM+ format 1 metadata only.	Same as above with exception as noted. This is the "Band 4 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 3, where a bit set condition (=1) indicates "Band 4 ON state."

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (16 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
SCENE_BAND5_ PRESENT	1	(Same as SCENE_BAND1_PRESENT values and format). This field is included in the ETM+ format 1 metadata only.	Same as above with exception as noted. This is the "Band 5 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 4, where a bit set condition (=1) indicates "Band 5 ON state."
SCENE_BAND6_ PRESENT	1	(Same as SCENE_BAND1_PRESENT values and format). This field is included in the ETM+ format 1 or format 2 metadata.	Same as above with exception as noted. This is the "Band 6/MIR ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 5, where a bit set condition (=1) indicates "Band 6 ON state."
SCENE_BAND7_ PRESENT	1	(Same as SCENE_BAND1_PRESENT values and format). This field is included in the ETM+ format 2 metadata only.	Same as above with exception as noted. This is the "Band 7 ON" status information obtained from PCD Serial Word "B" (major frame (2), minor frame 32, word 72), bit 6, where a bit set condition (=1) indicates "Band 7 ON state."
SCENE_BAND8_ PRESENT	1	(Same as SCENE_BAND1_PRESENT values and format). This field is included in the ETM+ format 2 metadata only.	Same as above with exception as noted. This is the "Band 8 ON" status information obtained from PCD Serial Word "E" (major frame (2), minor frame 35, word 72), bit 0, where a bit set condition (=1) indicates "Band 8 ON state."
BAND1_GAIN	1	= "L" for a low-gain condition = "H" for a high-gain condition This field is included in the ETM+ format 1 metadata only.	The band gain condition detected at the start of a WRS scene. This information is obtained from Words 7 and 8 of the PCD/Status Data field of the first error-free VCDU in a WRS scene.
BAND2_GAIN	1	= "L" for a low-gain condition = "H" for a high-gain condition This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_GAIN.)
BAND3_GAIN	1	= "L" for a low-gain condition = "H" for a high-gain condition This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_GAIN.)

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (17 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
BAND4_GAIN	1	= "L" for a low-gain condition = "H" for a high-gain condition This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_GAIN.)
BAND5_GAIN	1	= "L" for a low-gain condition = "H" for a high-gain condition This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_GAIN.)
BAND6_GAIN	1	= "L" for a low-gain condition = "H" for a high-gain condition This field is included in the ETM+ format 1 or format 2 metadata.	(See parameter description for BAND1_GAIN.)
BAND7_GAIN	1	= "L" for a low-gain condition = "H" for a high-gain condition This field is included in the ETM+ format 2 metadata only.	(See parameter description for BAND1_GAIN.)
BAND8_GAIN	1	= "L" for a low-gain condition = "H" for a high-gain condition This field is included in the ETM+ format 2 metadata only.	(See parameter description for BAND1_GAIN.)
BAND1_GAIN_CHANGE	1	= "0" indicates no band gain change within scene or = "+" indicates a low to high band gain change within scene or = "–" indicates a high to low band gain change within scene This field is included in the ETM+ format 1 metadata only.	Band gain change flags are generated by LPS by evaluating corresponding band gain states in adjacent ETM+ scans (major frames).
BAND2_GAIN_CHANGE	1	(Same as for BAND1_GAIN_CHANGE) This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_GAIN_CHANGE.)
BAND3_GAIN_CHANGE	1	(Same as for BAND1_GAIN_CHANGE) This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_GAIN_CHANGE.)
BAND4_GAIN_CHANGE	1	(Same as for BAND1_GAIN_CHANGE) This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_GAIN_CHANGE.)

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (18 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
BAND5_GAIN_CHANGE	1	(Same as for BAND1_GAIN_CHANGE) This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_GAIN_CHANGE.)
BAND6_GAIN_CHANGE	1	(Same as for BAND1_GAIN_CHANGE) This field is included in the ETM+ format 1 or format 2 metadata.	(See parameter description for BAND1_GAIN_CHANGE.)
BAND7_GAIN_CHANGE	1	(Same as for BAND1_GAIN_CHANGE) This field is included in the ETM+ format 2 metadata only.	(See parameter description for BAND1_GAIN_CHANGE.)
BAND8_GAIN_CHANGE	1	(Same as for BAND1_GAIN_CHANGE) This field is included in the ETM+ format 2 metadata only.	(See parameter description for BAND1_GAIN_CHANGE.)
BAND1_SL_GAIN_ CHANGE	1–5	= NNNNN where 0 = No gain change 1–12000 = Scan line number where the first change in band gain was detected. This field is included in the ETM+ format 1 metadata only.	This field indicates the scan line number in the scene for the first change detected in the band gain condition.
BAND2_SL_GAIN_ CHANGE	1–5	(Same as for BAND1_SL_GAIN_CHANGE) This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_SL_GAIN_CHANGE.)
BAND3_SL_GAIN_ CHANGE	1–5	(Same as for BAND1_SL_GAIN_CHANGE) This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_SL_GAIN_CHANGE.)
BAND4_SL_GAIN_ CHANGE	1–5	(Same as for BAND1_SL_GAIN_CHANGE) This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_SL_GAIN_CHANGE.)
BAND5_SL_GAIN_ CHANGE	1–5	(Same as for BAND1_SL_GAIN_CHANGE) This field is included in the ETM+ format 1 metadata only.	(See parameter description for BAND1_SL_GAIN_CHANGE)
BAND6_SL_GAIN_ CHANGE	1–5	(Same as for BAND1_SL_GAIN_CHANGE) This field is included in the ETM+ format 1 or format 2 metadata.	(See parameter description for BAND1_SL_GAIN_CHANGE)

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (19 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
BAND7_SL_GAIN_ CHANGE	1–5	(Same as for BAND1_SL_GAIN_CHANGE) This field is included in the ETM+ format 2 metadata only.	(See parameter description for BAND1_SL_GAIN_CHANGE)
BAND8_SL_GAIN_ CHANGE	1–5	(Same as for BAND1_SL_GAIN_CHANGE) This field is included in the ETM+ format 2 metadata only.	(See parameter description for BAND1_SL_GAIN_CHANGE)
FULL_APERTURE_CAL_ FLAG	1	= "N" indicates no full calibration activity during this scene or = "Y" indicates a full calibration activity	This field indicates the ETM+ full calibration activity during this scene. The calibration door activity flag is interpolated from “serial word P” of the third PCD major frame, minor frame 83, word 72, bits 2 and 3.
DAY_NIGHT_FLAG	1	= "D" for day flag 'True' or = "N" for night flag 'True'	This field indicates the day or night condition for the scene. The LPS determines the day/night condition of a scene by comparing the Sun elevation values against an angle value of 0 degrees. A scene is declared a day scene if the Sun elevation angle is greater than 0 degrees; otherwise it is declared a night scene.
END_GROUP	12	= WRS_SCENE_NN where NN = 01–99 (Up to 35 full scenes are expected to be received by LPS in a 14-minute subinterval)	End of the third level ODL group. It indicates the end of the ETM+ format 1 or format 2 WRS Scene metadata group records.
Image Q&A Data The following parameter values are repeated for each WRS scene included in this subinterval.			
GROUP	9	= ETM_QA_NN where NN = 01–99	Beginning of the third level ODL group. It indicates the beginning of the ETM+ format 1 or format 2 Scene NN Q&A data group records.
SCENE_QUALITY	3	= 00–99, –1	The first digit represents image quality; the second PC quality. A 99 represents the highest quality and a 00 the lowest quality. A –1 occurs if no scene quality score was obtained.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (20 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
CADUS_VCDUS_ RECEIVED	1–6	= 1–999999	The total number of CADUs/VCDUs received for this scene. Approximately 362,380 VCDUs are expected to be received for a 26.8-second long WRS scene. A WRS scene consists of a maximum of 375, including 40 overlap scans.
FLY_WHEEL_CADUS	1–6	= 0–999999	The total number of CADUs fly-wheeled due to sync errors.
RS_ERR_VCDUS	1–6	= 0–999999	The total number of VCDUs with Reed-Solomon error corrected in the header field.
BCH_CORRECTED_ VCDUS	1–6	= 0–999999	The total number of VCDUs with BCH errors corrected for up to 3 bits in their mission data fields.
BCH_UNCORRECTED_ VCDUS	1–6	= 0–999999	The total number of VCDUs containing uncorrected BCH errors (bits) in their mission data fields.
BIT_ERROR_RATE	1–4	= 0–9999	The number of bit errors detected over the whole length of the scene and normalized to average number of errors in 100,000 bits. BIT_ERROR_RATE = (Total Detected Bit Errors/Total Number of Bits in Subinterval) x 100,000. This BER is calculated using bit errors detected (corrected or not) during CRC and BCH checks of the input VCDUs. An input data bit error rate of 1 in 100,000 or less is considered acceptable.
ETM_TIMECODE_ ERRORS	1–3	0–375	The total number of ETM+ scans (major frames) detected with errors in their time code fields during processing of this subinterval scene. A maximum of 375 ETM+ scans are possible in a WRS scene.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (21 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
ENTIRELY_FILLED_ SCANS	1–3	0–375	The total number of ETM+ major frames (maximum of 375) in this WRS scene (~26.8 seconds for 375 scans) that were entirely filled using a predetermined fill data pattern.
PARTIALLY_FILLED_ SCANS	1–3	0–375	The total number of ETM+ major frames (maximum of 375) in this WRS scene that were partially filled using a predetermined fill data pattern.
END_GROUP PCD Q&A Data	9	= ETM_QA_NN where NN = 01–99	End of the third level ODL group. It indicates the end of the ETM+ Q&A data group records for WRS Scene NN.
PCD Q&A Data The following parameter values are repeated for each WRS scene included in the subinterval.			
GROUP	9	= PCD_QA_NN where NN = 01–99	Beginning of the third level ODL group. It indicates the beginning of the PCD Q&A data group records for WRS Scene NN.
PCD_WORDS_ RECEIVED	1–6	= 0–999999	The total number of PCD words, extracted from the unpacked PCD words (one sync byte, 3 repeated data bytes, and at least 4 fill bytes), received for this scene. Approximately 107,200 packed PCD words can be received by LPS for a 26.8-second scene.
PCD_BYTE_VOTING_ ERR	1–6	= 0–999999	The total number of PCD words that encountered byte-voting errors during packing (for a maximum of 107,200 words).
TOTAL_PCD_MINOR_ FRAMES	1–3	= 0–999	The total number of PCD minor frames constructed during this scene. Approxi-mately 838 PCD minor frames can be received by LPS for a 26.8-second WRS scene.
PCD_MINOR_FRAME_ ERR	1–3	= 0–999	The total number of PCD minor frames which encountered sync errors during their construction for a scene. Up to 838 minor frames for a WRS scene are expected.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (22 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
Processed PCD Q&A Data			
FILLED_PCD_MINOR_ FRAMES	1–3	= 0–999	The total number of PCD minor frames which required a data fill during their construction.
FILLED_PCD_MAJOR_ FRAMES	1	= 0–9	The total number of PCD major frames which required a data fill during their construction. Approximately 7 major frames can be received by LPS for a 26.8-second long WRS scene.
END_GROUP	9	= PCD_QA_NN where NN = 01–99	End of the third level ODL group. It indicates the end of the PCD Q&A data group records for WRS Scene NN.
GROUP	19	= PROCESSED_PCD_QA_NN where NN = 01–99	Beginning of the third level ODL group. It indicates the beginning of the processed PCD Q&A data group records for WRS Scene NN.
TOTAL_ATTITUDE_ POINTS	1	= 0–9	The total number of spacecraft attitude data points (quaternations) received and processed from the PCD associated with this scene. Approximately 6.5 spacecraft attitude data points can be received for a 26.8-second WRS scene.
REJECTED_ATTITUDE_ POINTS	1	= 0–9	The total number of spacecraft attitude data points (quaternations) found to fail the PCD quality checks. The rejected data points are flagged and included in the PCD file associated with this WRS scene.
MISSING_ATTITUDE_ POINTS	1	= 0–9	The total number of spacecraft attitude data points (quaternations) found missing during PCD quality checks. The missing data points are flagged and included in the PCD file associated with this WRS scene.

Table 5–6. LPS Metadata File Contents—ODL Parameter Values (23 of 23)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
TOTAL_EPHEMERIS_ POINTS	1	= 0–9	The total number of ephemeris data points received and processed from the PCD of this scene. Approximately 7 ephemeris data points can be received for a 26.8-second long WRS scene.
REJECTED_EPHEMERIS _POINTS	1	= 0–9	The total number of spacecraft ephemeris data points found to fail LPS PCD quality checks. Rejected data points are flagged and included in the PCD file associated with this WRS scene.
MISSING_EPHEMERIS_ POINTS	1	= 0–9	The total number of spacecraft ephemeris data points found missing during PCD quality checks. The missing data points are flagged and included in the PCD file associated with this WRS scene.
END_GROUP	19	= PROCESSED_PCD_QA_NN where NN = 01–99	End of the third level ODL group. It indicates the end of the processed PCD Q&A data group records for WRS Scene NN.
END_GROUP	17	= METADATA_SCENE_NN where NN = 01–99 (Up to 35 full scenes are expected to be received by LPS in a 14-minute subinterval.)	End of the second level ODL group. It indicates the end of the ETM+ format 1 or format 2 scene NN level metadata group records.
END_GROUP	26	= SUBINTERVAL_ METADATA_FMT_m where m = 1 for format 1, or 2 for format 2	End of the second level ODL group. It indicates the end of the ETM+ format 1 or format 2 subinterval level metadata group records.
END_GROUP	13	= METADATA_FILE	End of the first level ODL group. It indicates the end of the LPS metadata file level group records for an ETM+ format 1 or format 2 subinterval.
END			Required standalone parameter signifying file end.

5.3.4.2 ECS Metadata

The third metadata file, also an external element, is created during product generation and contains information specific to the product ordered such as corner coordinates and external element file names. The full contents of the ECS metadata file are listed in Table 5–7.

Table 5–7. ECS Product Metadata File Contents—ODL Parameter Values (1 of 8)

Vdata Name: "L7XsssfnYYDOYHHuuv.MTP"
Vdata Class: Product_Metadata
Interlace Type: FULL_INTERLACE
Bytes Per Logical Record: 65536
Number of Records: One record.
Field Name: Metadata_Product_Specific
Data Type: Char8 Count: 65536

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
GROUP	17	= ECS_METADATA_FILE	Beginning of the first level ODL group. It indicates the start of the ECS metadata file level group.
GROUP	18	= METADATA_FILE_INFO	Beginning of metadata file information group.
PRODUCT_CREATION_ DATE_TIME	20	= YYYY-MM-DDThh:mm:ssZ where YYYY = 4-digit Julian year (e.g., 1998 and 2001) MM = Month number of a Julian year (01–12 for January to December) DD = Day of a Julian month (01–31) T indicates the start of time information in the ODL ASCII time code format hh = Hours (00–23) mm = Minutes (00–59) ss = Seconds (00–59) Z indicates "Zulu" time (same as GMT)	The ECS system date and time when the metadata file for a Level 0R product set was created. For ease of human readability, this date and time information is presented in the ODL ASCII format. The time is expressed as Universal Coordinated Time (also known as Greenwich Mean Time (GMT)). Insertion of additional characters "T" and "Z" is required to meet the ODL ASCII time format.
STATION_ID	3	= "EDC"	Unique three-letter code identifying the origination ground station.
END_GROUP	18	= METADATA_FILE_INFO	End of the metadata information group.
GROUP	16	= PRODUCT_METADATA	Beginning of the product metadata group.

Table 5–7. ECS Product Metadata File Contents—ODL Parameter Values (2 of 8)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
PRODUCT_TYPE	3	= "L0R"	Type of product as opposed to Level-1 radiometrically corrected (L1R).
SPACECRAFT_ID	8	= "Landsat7"	Name of the satellite platform.
SENSOR_ID	4	= "ETM+"	Name of the imaging sensor.
ACQUISITION_DATE	10	YYYY-MM-DD where (See data and time convention above.)	Date the image was acquired. The value in the case of Subinterval product is to be derived from modification (datetime to date) of the value from SUBINTERVAL_START_TIME, and the value in the case of Scene product is to be derived from modification of SCENE_CENTER_SCAN_TIME.
STARTING_PATH	3	= NNN, where NNN = Path number	Starting WRS path value for product.
STARTING_ROW	3	= NNN, where NNN = Row of the first full or partial scene in the product	Starting WRS row.
ENDING_ROW	3	= NNN, where NNN = Row of the last full or partial scene in the product	Ending WRS row.
TOTAL_WRS_SCENES	5	= NN.NN, where NN.NN = Number of full and partial scenes encapsulated by the product	Maximum number is 36.99 for a subinterval product.
NUMBER_OF_SCANS	5	= NNNNN, where NNNNN = 90–12410	Total number of scans in the product.
STARTING_SUBINTERVAL_SCAN	5	= NNNNN, where NNNNN = 1–12321	Product starting scan number referenced relative to the parent subinterval.
ENDING_SUBINTERVAL_SCAN	5	= NNNNN, where NNNNN = 90–12410	Product ending scan number referenced relative to the parent subinterval.
BAND_COMBINATION	9	“NNNNNNNNN”, where “NNNNNNNNN” = e.g. 123456678 for all bands present, 123-----8 for bands 1,2,3,8. A '-' is a position holder for absent bands	ECS-generated bands present indicator for the product ordered. The first 6 is format 1 band 6. The second 6 is format 2 band 6.

Table 5–7. ECS Product Metadata File Contents—ODL Parameter Values (3 of 8)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
PRODUCT_UL_CORNER_LAT	8	= –90.0000 through +90.0000 degrees (with a 4-digit precision) A positive (+) value indicates north latitude. A negative (–) value indicates south latitude.	ECS-calculated "actual" latitude value for the upper left corner of the product. LPS-calculated value is used for scene products.
PRODUCT_UL_CORNER_LON	8	= –180.0000 through +180.0000 degrees (with a 4-digit precision) A positive (+) value indicates east longitude. A negative (–) value indicates west longitude.	ECS-calculated "actual" longitude value for the upper left corner of the product. LPS-calculated value is used for scene products.
PRODUCT_UR_CORNER_LAT	8	= –90.0000 through +90.0000 degrees (with a 4-digit precision)	ECS-calculated "actual" latitude value for the upper right corner of the product. LPS-calculated value is used for scene products.
PRODUCT_UR_CORNER_LON	9	= –180.0000 through +180.0000 degrees (with a 4-digit precision)	ECS-calculated "actual" longitude value for the upper right corner of the product. LPS-calculated value is used for scene products.
PRODUCT_LL_CORNER_LAT	8	= –90.0000 through +90.0000 degrees (with a 4-digit precision)	ECS-calculated "actual" latitude value for the lower left corner of the product. LPS-calculated value is used for scene products.
PRODUCT_LL_CORNER_LON	9	= –180.0000 through +180.0000 degrees (with a 4-digit precision)	ECS-calculated "actual" longitude value for the lower left corner of the product. LPS-calculated value is used for scene products.
PRODUCT_LR_CORNER_LAT	8	= –90.0000 through +90.0000 degrees (with a 4-digit precision)	ECS-calculated "actual" latitude value for the lower right corner of the product. LPS-calculated value is used for scene products.
PRODUCT_LR_CORNER_LON	9	= –180.0000 through +180.0000 degrees (with a 4-digit precision)	ECS-calculated "actual" longitude value for the lower right corner of the product. LPS-calculated value is used for scene products.

Table 5–7. ECS Product Metadata File Contents—ODL Parameter Values (4 of 8)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
BAND1_GAIN	1	= "L" for low or "H" for high	Gain state for band 1's first data line if part of the product.
BAND2_GAIN	1	= "L" for low or "H" for high	Gain state for band 2's first data line if part of the product.
BAND3_GAIN	1	= "L" for low or "H" for high	Gain state for band 3's first data line if part of the product.
BAND4_GAIN	1	= "L" for low or "H" for high	Gain state for band 14s first data line if part of the product.
BAND5_GAIN	1	= "L" for low or "H" for high	Gain state for band 5's first data line if part of the product.
BAND6_GAIN_F1	1	= "L" for low or "H" for high	Gain state for band 6's first data line if part of the product - format 1.
BAND6_GAIN_F2	1	= "L" for low or "H" for high	Gain state for band 6's first data line if part of the product - format 2.
BAND7_GAIN	1	= "L" for low or "H" for high	Gain state for band 7's first data line if part of the product.
BAND8_GAIN	1	= "L" for low or "H" for high	Gain state for band 8's first data line if part of the product.
BAND1_FILE_NAME	32	"L7Xsss1nYYDOYHHuuv_B10.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), YYDOYHHMM = ECS-generated extension where YY = Year product was created DOY = Day of year product was created HH = Hour product was created MM = Minute product was created	ECS-generated external element file name for band 1.
BAND2_FILE_NAME	32	"L7Xsss1nYYDOYHHuuv_B20.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for band 2.

Table 5–7. ECS Product Metadata File Contents—ODL Parameter Values (5 of 8)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
BAND3_FILE_NAME	32	"L7Xsss1nYYDOYHHuuv_B30.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for band 3.
BAND4_FILE_NAME	32	"L7Xsss1nYYDOYHHuuv_B40.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for band 4.
BAND5_FILE_NAME	32	"L7Xsss1nYYDOYHHuuv_B50.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for band 5.
BAND6_FILE_NAME_F1	32	"L7Xsss1nYYDOYHHuuv_B60.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for band 6, format 1.
BAND6_FILE_NAME_F2	32	"L7Xsss2nYYDOYHHuuv_B60.YYDOYHHMM" where L7Xsss2nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for band 6, format 2.
BAND7_FILE_NAME	32	"L7Xsss2nYYDOYHHuuv_B70.YYDOYHHMM" where L7Xsss2nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for band 7.

Table 5–7. ECS Product Metadata File Contents—ODL Parameter Values (6 of 8)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
BAND8_FILE1_NAME BAND8_FILE2_NAME BAND8_FILE3_NAME	32	"L7Xsss2nYYDOYHHuuv_B81.YYDOYHHMM" where L7Xsss2nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for band 8. The file extensions precursors B81, B82, B83, are used for a band 8 that spans multiple files.
IC_DATA_FILE_NAME_F1	32	"L7Xsss1nYYDOYHHuuv_CAL.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for format 1 internal calibrator data.
IC_DATA_FILE_NAME_F2	32	"L7Xsss2nYYDOYHHuuv_CAL.YYDOYHHMM" where L7Xsss2nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for format 2 internal calibrator data.
SCAN_OFFSETS_FILE_NAME_F1	32	"L7Xsss1nYYDOYHHuuv_SLO.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for format 1 scan line shifts.
SCAN_OFFSETS_FILE_NAME_F2	32	"L7Xsss2nYYDOYHHuuv_SLO.YYDOYHHMM" where L7Xsss2nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for format 2 scan line shifts.
MSCD_FILE_NAME_F1	32	"L7Xsss1nYYDOYHHuuv_MSD.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for format 1 MSCD.

Table 5–7. ECS Product Metadata File Contents—ODL Parameter Values (7 of 8)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
MSCD_FILE_NAME_F2	32	"L7Xsss2nYYDOYHHuuv_MSD .YYDOYHHMM" where L7XsssfnYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for format 2 MSCD.
PCD_FILE_NAME_F1	32	"L7Xsss1nYYDOYHHuuv_PCD. YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for format 1 PCD.
PCD_FILE_NAME_F2	32	"L7Xsss2nYYDOYHHuuv_PCD. YYDOYHHMM" where L7Xsss2nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for format 2 PCD.
METADATA_FILE_NAME_ F1	32	"L7Xsss1nYYDOYHHuuv_ MTA.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for ECS format 1 metadata.
METADATA_FILE_NAME_ F2	32	"L7Xsss2nYYDOYHHuuv_ MTA.YYDOYHHMM" where L7Xsss2nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for ECS format 2 metadata. Although not format specific, a 1 is used in the file name if format 1 exists. Otherwise, the 2 from format 2 is used.
METADATA_PS_FILE_ NAME	32	"L7Xsss1nYYDOYHHuuv_ MTP.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for ECS product-specific metadata. Although not format specific, a 1 is used in the file name if format 1 exists. Otherwise, the 2 from format 2 is used.

Table 5–7. ECS Product Metadata File Contents—ODL Parameter Values (8 of 8)

Parameter Name	Size (ASCII bytes)	Value, Format, Range, and Units	Parameter Description/Remarks
CPF_FILE_NAME	35	"L7CPFYYYYMMDD_YYYYMMDD_nn.YYDOYHHMM" where YYYYMMDD = Effective start date and effective end date, respectively nn = Incrementing version number within a 90-day period (00–99). - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for the IAS calibration parameter file. Note: The version number 00 is reserved exclusively for the prelaunch CPF.
GEOLOCATION_FILE_NAME	32	"L7Xsss1nYYDOYHHuuv_GEO.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated external element file name for the geolocation table. Although not format specific, a 1 is used in the file name if format 1 exists. Otherwise, the 2 from format 2 is used.
HDF_DIR_FILE_NAME	32	"L7Xsss1nYYDOYHHuuv_HDF.YYDOYHHMM" where L7Xsss1nYYDOYHH = (see 5.3.1 for details), - YYDOYHHMM = ECS-generated extension (see details above)	ECS-generated file name for the HDF directory file. Although not format specific, a 1 is used in the file name if format 1 exists. Otherwise, the 2 from format 2 is used.
END_GROUP	16	= PRODUCT_METADATA	End of the product metadata group.
END_GROUP	17	= ECS_METADATA_FILE	End of the ECS product metadata ODL group.
END			Required standalone parameter signifying file end.

5.3.4.3 ODL Conventions

All metadata are stored as ASCII text using the ODL syntax developed by the Jet Propulsion Laboratory. ODL is a tagged keyword language that was developed to provide a human-readable data structure to encode data for simplified interchange. Parameters defined by the ODL syntax can be logically grouped to aid in file organization and efficient parsing by software interpreters. ODL details can be found in the *Planetary Data System Standards Reference*, Chapter 12, "Object Description Language Specification and Usage," (see Section 1.4, Applicable Document 6.)

The ODL syntax employs the following conventions:

- Parameter definition is in the form of parameter = value.
- There is one parameter definition per line.

- Blank spaces and lines are ignored.
- A carriage return <CR> and line feed <LF> end each line in the file.
- Each line of comments must begin with the character /* and end with the character */, including comments embedded on the same line as a parameter definition.
- Quotation marks are required for values that are text strings, including single characters.
- Exceptions to this rule are the GROUP, END_GROUP, OBJECT, and END_OBJECT.
- Identifiers or values, which do not use quotation marks.
- Case is not significant, but uppercase is used for parameter and group names to aid in readability.
- Indentation is not significant, but is used for readability.
- The reserve word END concludes the file.

5.3.4.4 ODL Examples

The three metadata files included in a 0R product conform to the ODL standard. Table 5–6 provides details on LPS parameter values and their formats used to construct the ETM+ format 1 and format 2 metadata files. Table 5–7 provides similar details for building the ECS 0R product metadata file. In accordance with the ODL standard, all parameters and values are presented using ASCII standard characters.

Examples of the three ODL metadata files follow. The GROUP keyword and names are presented as bold text for illustration purposes only. In addition, the comment statements enclosed within "/*" and "*/" are shown to clarify the metadata format construction. They can be used but are not required in the ODL metadata file format.

5.3.4.4.1 HDF ODL Example—Format 1 Metadata File

Format 1 metadata is organized into subinterval and scene groups. A scene group exists for each scene in the subinterval.

```
     /*  LPS Level 0R subinterval - format 1 metadata file - Format 1  */

GROUP = METADATA_FILE;

         /*   Metadata file identification - Format 1   */

         GROUP = METADATA_FILE_INFO
            FILE_NAME = "L71EDC119813511010.MTA"
            FILE_CREATION_ DATE_TIME = 1999-02-01T13:30:26Z
            FILE_VERSION_NO = 0
            STATION_ID = "EDC"
            SOFTWARE_VERSION_NO = “2.1.0”
            L7_CPF_NAME = “L7CPF19990101_19990331.01”
         END_GROUP = METADATA_FILE_INFO
```

```
/* Subinterval level metadata - Format 1 */

GROUP = SUBINTERVAL_METADATA_FMT_1
   SPACECRAFT_ID = "Landsat7"
   SENSOR_ID = "ETM+"
   CONTACT_PERIOD_START_TIME = 1999-031T22:23:10Z
   CONTACT_PERIOD_STOP_TIME = 1999-031T22:37:01Z
   STARTING_PATH = 029
   STARTING_ROW = 020
   ENDING_ROW = 045
   SUBINTERVAL_START_TIME = 1999-031T16:55:18.1234567Z
   SUBINTERVAL_STOP_TIME = 1999-031T05:40.7654321Z
   TOTAL_ETM_SCANS = 8853
   PCD_START_TIME = 1999-031T16:49:18.1234567Z
   PCD_STOP_TIME = 1999-031T17:23:40.7654321Z
   TOTAL_PCD_MAJOR_FRAMES = 147
   SUBINTERVAL_UL_CORNER_LAT = 41.5432    /* Sample Results are */
   SUBINTERVAL_UL_CORNER_LON = -96.5432   /* shown; not related*/
   SUBINTERVAL_UR_CORNER_LAT = 41.4321    /*  to other results */
   SUBINTERVAL_UR_CORNER_LON = -96.6543   /* included in this */
   SUBINTERVAL_LL_CORNER_LAT = 41.4532    /* Example */
   SUBINTERVAL_LL_CORNER_LON = -96.3543
   SUBINTERVAL_LR_CORNER_LAT = 41.3432
   SUBINTERVAL_LR_CORNER_LON = -96.6543
   ETM_LAST_ON_TIME   = 1999-031T11:20:01.1234567Z

   ETM_LAST_OFF_TIME = 1999-031T09:25:01.7654321Z
   UT1_CORRECTION = 0.12345
   BAND1_PRESENT = "Y"
   BAND2_PRESENT = "Y"
   BAND3_PRESENT = "Y"
   BAND4_PRESENT = "Y"
   BAND5_PRESENT = "Y"
   BAND6_PRESENT = "Y"
   TOTAL_WRS_SCENES = 26
   PARTIAL_WRS_SCENES = 2
   TOTAL_FILES = 35
   BAND1_FILE_NAME =      "L71EDC119903122010.B10"
   BAND2_FILE_NAME =      "L71EDC119903122010.B20"
   BAND3_FILE_NAME =      "L71EDC119903122010.B30"
   BAND4_FILE_NAME =      "L71EDC119903122010.B40"
   BAND5_FILE_NAME =      "L71EDC119903122010.B50
   BAND6_FILE_NAME =      "L71EDC119903122010.B60"
   MSCD_FILE_NAME =       "L71EDC119903122010.MSD"
   PCD_FILE_NAME =        "L71EDC119903122010.PCD"
   CAL_FILE_NAME =        "L71EDC119903122010.CAL"

/* Metadata for all WRS scenes included in the format 1 subinterval */
/* Note:  The WRS scene centers correspond to band 1 scan times */

GROUP =  METADATA_SCENE_01
   GROUP = WRS_SCENE_01
      WRS_SCENE_NO = 1
      FULL_OR_PARTIAL_SCENE = "P"
      BROWSE_FILE_NAME = "L71EDC119813511010.R01"
      WRS_PATH = 029
      WRS_ROW = 020
      SCENE_CENTER_SCAN_NO = 95
```

```
                SCENE_CENTER_SCAN_TIME = 1999-031T16:55:30.1234567Z
                SCENE_CENTER_LAT = 42.1234
                SCENE_CENTER_LON = -96.7654
                HORIZONTAL_DISPLAY_SHIFT = 275
                SCENE_UL_CORNER_LAT = 41.5432
                SCENE_UL_CORNER_LON = -96.5432
                SCENE_UR_CORNER_LAT = 41.4321
                SCENE_UR_CORNER_LON = -96.6543
                SCENE_LL_CORNER_LAT = 41.6543
                SCENE_LL_CORNER_LON = -96.3543
                SCENE_LR_CORNER_LAT = 41.3432
                SCENE_LR_CORNER_LON = -96.6543
                SCENE_CCA = 52
                UL_QUAD_CCA = 99
                UR_QUAD_CCA = 99
                LL_QUAD_CCA = 4
                LR_QUAD_CCA = 6
                ACCA_ALGORITHM_ID_VER = "ACCA_31JAN97_LSO20.ALG"
                SUN_AZIMUTH_ANGLE = 20.1234567
                SUN_ELEVATION_ANGLE = 13.8234567
                SCENE_BAND1_PRESENT = "Y"
                SCENE_BAND2_PRESENT = "Y"
                SCENE_BAND3_PRESENT = "Y"
                SCENE_BAND4_PRESENT = "Y"
                SCENE_BAND5_PRESENT = "Y"
                SCENE_BAND6_PRESENT = "Y"
                BAND1_GAIN = "H"
                BAND2_GAIN = "H"
                BAND3_GAIN = "H"
                BAND4_GAIN = "H"
                BAND5_GAIN = "H"
                BAND6_GAIN = "L"
                BAND1_GAIN_CHANGE = "0"
                BAND2_GAIN_CHANGE = "0"
                BAND3_GAIN_CHANGE = "0"
                BAND4_GAIN_CHANGE = "0"
                BAND5_GAIN_CHANGE = "-"
                BAND6_GAIN_CHANGE = "0"
                BAND1_SL_GAIN_CHANGE = 0
                BAND2_SL_GAIN_CHANGE = 0
                BAND3_SL_GAIN_CHANGE = 0
                BAND4_SL_GAIN_CHANGE = 0
                BAND5_SL_GAIN_CHANGE = 9000
                BAND6_SL_GAIN_CHANGE = 0
                FULL_APERTURE_CAL_FLAG = "N"
                DAY_NIGHT_FLAG = "D"

END_GROUP = WRS_SCENE_01

      /* Scene image data quality and accounting (Q&A) data */

            GROUP =  ETM_QA_01
                SCENE_QUALITY = -99
                CADUS_VCDUS_RECEIVED = 543926
                FLY_WHEEL_CADUS = 123456
                RS_ERR_VCDUS = 123
                BCH_CORRECTED_VCDUS = 456
                BCH_UNCORRECTED_VCDUS = 12
```

```
               BIT_ERROR_RATE = 10
               ETM_TIMECODE_ERRORS = 12
               ENTIRELY_FILLED_SCANS = 12
               PARTIALLY_FILLED_SCANS = 123
            END_GROUP =  ETM_QA_01

      /* Scene PCD quality and accounting information */

            GROUP =  PCD_QA_01
               PCD_WORDS_RECEIVED = 106340
               PCD_BYTE_VOTING_ERR = 106
               TOTAL_PCD_MINOR_FRAMES = 202
               PCD_MINOR_FRAME_ERR = 202
               FILLED_PCD_MINOR_FRAMES = 200
               FILLED_PCD_MAJOR_FRAMES = 1
            END_GROUP =  PCD_QA_01

      /* Process PCD quality and accounting information */

            GROUP =  PROCESSED_PCD_QA_01
               TOTAL_ATTITUDE_POINTS = 6
               REJECTED_ATTITUDE_POINTS = 1
               MISSING_ATTITUDE_POINTS = 1
               TOTAL_EPHEMERIS_POINTS = 6
               REJECTED_EPHEMERIS_POINTS = 1
               MISSING_EPHEMERIS_POINTS = 1
            END_GROUP =  PROCESSED_PCD_QA_01

         END_GROUP =  METADATA_SCENE_01

               •  /* Repeat  METADATA_SCENE_NN GROUP until NN > 26, */
               •  /* the total number of WRS scenes, full or partial, */
               •  /* present in this subinterval example */

         GROUP =  METADATA_SCENE_26/* Scene NN Metadata ODL group */

         END_GROUP =  METADATA_SCENE_26

      END_GROUP = SUBINTERVAL_METADATA_FMT_1

END_GROUP = METADATA_FILE

END
```

5.3.4.4.2 HDF ODL Example—Format 2 Metadata File

Format 2 metadata are organized into subinterval and scene groups. A scene group exists for each scene in the subinterval.

```
       /*     LPS Level 0R subinterval - format 2 metadata file -     */

GROUP = METADATA_FILE

         /* Metadata file identification - Format 2 */

         GROUP = METADATA_FILE_INFO
            FILE_NAME = "L71EDC119903122010.MTA"
```

```
            FILE_CREATION_ DATE_TIME = 1999-02-01T13:30:26Z
            FILE_VERSION_NO = 0
            STATION_ID = "EDC"
            SOFTWARE_VERSION_NO = “2.1.0”
            L7_CPF_NAME = “L7CPF19990101_19990331.01”
         END_GROUP = METADATA_FILE_INFO

       /* PRODUCT level metadata - Format 2 */

         GROUP = SUBINTERVAL_METADATA_FMT_2
            SPACECRAFT_ID = "Landsat7"
            SENSOR_ID = "ETM+"
            CONTACT_PERIOD_START_TIME = 1999-031T22:23:10Z
            CONTACT_PERIOD_STOP_TIME = 1999-031T22:37:01Z
            STARTING_PATH = 029
            STARTING_ROW = 020
            ENDING_ROW = 045
            SUBINTERVAL_START_TIME = 1999-031T16:55:18.1234567Z
            SUBINTERVAL_STOP_TIME = 1999-031T17:05:40.7654321Z
            TOTAL_ETM_SCANS = 8853
            PCD_START_TIME = 1999-031T16:49:18.1234567Z
            PCD_STOP_TIME = 1999-031T17:23:40.7654321Z
            TOTAL_PCD_MAJOR_FRAMES = 147
            SUBINTERVAL_UL_CORNER_LAT = 41.5432    /* Sample results are */
            SUBINTERVAL_UL_CORNER_LON = –96.5432   /* shown not related to*/
            SUBINTERVAL_UR_CORNER_LAT = 41.4321    /* other results included*/
            SUBINTERVAL_UR_CORNER_LON = –96.6543   /* in this example */
            SUBINTERVAL_LL_CORNER_LAT = 41.4532
            SUBINTERVAL_LL_CORNER_LON = –96.3543
            SUBINTERVAL_LR_CORNER_LAT = 41.3432
            PRODUCT_LR_CORNER_LON = –96.6543
            ETM_LAST_ON_TIME = 1999-135T11:15:01.1234567Z
            ETM_LAST_OFF_TIME = 1999-135T09:25:01.7654321Z
            UT1_CORRECTION = 0.1234567
            BAND6_PRESENT = "Y"
            BAND7_PRESENT = "Y"
            BAND8_PRESENT = "Y"
            TOTAL_WRS_SCENES = 26
            PARTIAL_WRS_SCENES = 2
            TOTAL_FILES = 8
            BAND6_FILE_NAME = "L71EDC219903122010.B60"
            BAND7_FILE_NAME = "L71EDC219903122010.B70"
            BAND8_FILE1_NAME = "L71EDC219903122010.B81"
            BAND8_FILE2_NAME = "L71EDC219903122010.B82"
            BAND8_FILE3_NAME = "L71EDC219903122010.B83"
            MSCD_FILE_NAME = "L71EDC219903122010.MSD"
            PCD_FILE_NAME = "L71EDC219903122010.PCD"
            CAL_FILE_NAME = "L71EDC219903122010.CAL"

/* WRS scene-by-scene metadata for this Level 0R subinterval */
/* Note:  The WRS scene centers correspond to band 7 scan times */

         GROUP =  METADATA_SCENE_01

            GROUP = WRS_SCENE_01
               WRS_SCENE_NO = 1
               FULL_OR_PARTIAL_SCENE = "P"
               WRS_PATH = 029
```

```
            WRS_ROW = 020
            SCENE_CENTER_SCAN_NO = 95
            SCENE_CENTER_SCAN_TIME = 1999-031T16:55:30.1234567Z
            SCENE_CENTER_LAT = 42.1234
            SCENE_CENTER_LON = –96.7654
            HORIZONTAL_DISPLAY_SHIFT = 275
            SCENE_UL_CORNER_LAT = 41.5432
            SCENE_UL_CORNER_LON = –96.5432
            SCENE_UR_CORNER_LAT = 41.4321
            SCENE_UR_CORNER_LON = –96.6543
            SCENE_LL_CORNER_LAT = 41.6543
            SCENE_LL_CORNER_LON = –96.3543
            SCENE_LR_CORNER_LAT = 41.3434
            SCENE_LR_CORNER_LON = –96.6543
            SUN_AZIMUTH_ANGLE = 20.1234567
            SUN_ELEVATION_ANGLE = 13.8234567
            SCENE_BAND6_PRESENT = "Y"
            SCENE_BAND7_PRESENT = "Y"
            SCENE_BAND8_PRESENT = "Y"
            BAND6_GAIN = "H"
            BAND7_GAIN = "H"
            BAND8_GAIN = "H"
            BAND6_GAIN_CHANGE = "0"
            BAND7_GAIN_CHANGE = "-"
            BAND8_GAIN_CHANGE = "0"
            BAND6_SL_GAIN_CHANGE = 0
            BAND7_SL_GAIN_CHANGE = 9000
            BAND8_SL_GAIN_CHANGE = 0
            FULL_APERTURE_CAL_FLAG = "N"
            DAY_NIGHT_FLAG = "D"

         END_GROUP = WRS_SCENE_01

      /* Scene Image Data quality and accounting (Q&A) data */

         GROUP =  ETM_QA_01
            SCENE_QUALITY = –1
            CADUS_VCDUS_RECEIVED = 543926
            FLY_WHEEL_CADUS = 123456
            RS_ERR_VCDUS = 123
            BCH_CORRECTED_VCDUS = 456
            BCH_UNCORRECTED_VCDUS = 12
            BIT_ERROR_RATE = 99
            ETM_TIMECODE_ERRORS = 12
            ENTIRELY_FILLED_SCANS = 12
            PARTIALLY_FILLED_SCANS = 123
         END_GROUP =  ETM_QA_01

      /* Scene PCD quality and accounting information */

         GROUP =  PCD_QA_01
            PCD_WORDS_RECEIVED = 106341
            PCD_BYTE_VOTING_ERR = 106
            TOTAL_PCD_MINOR_FRAMES = 202
            PCD_MINOR_FRAME_ERR = 202
            FILLED_PCD_MINOR_FRAMES = 199
            FILLED_PCD_MAJOR_FRAMES = 1
         END_GROUP =  PCD_QA_01

      /* Processed PCD quality and accounting information on scene */
```

```
            GROUP =  PROCESSED_PCD_QA_01
               TOTAL_ATTITUDE_POINTS = 6
               REJECTED_ATTITUDE_POINTS = 1
               MISSING_ATTITUDE_POINTS = 1
               TOTAL_EPHEMERIS_POINTS = 6
               REJECTED_EPHEMERIS_POINTS = 1
               MISSING_EPHEMERIS_POINTS = 1
            END_GROUP =  PROCESSED_PCD_QA_01

         END_GROUP =  METADATA_SCENE_01

         •  /* Repeat METADATA_SCENE_NN GROUP until NN > 26, */
         •  /* the total number of WRS scenes, full or partial, present in */
         •  /* this subinterval example */

         GROUP =  METADATA_SCENE_26

            /* Scene NN Metadata ODL group */

         END_GROUP =  METADATA_SCENE_26

      END_GROUP = SUBINTERVAL_METADATA_FMT_2

END_GROUP = METADATA_FILE

END
```

5.3.4.4.3 HDF ODL Example—ECS Metadata File

This file is organized into information about the file and information about the product.

```
      /* Landsat 7 ECS Product Metadata Format  */

                  /*----------------------------------*/
                  /*      Metadata File Header  */
                  /*----------------------------------*/

GROUP=ECS_METADATA_FILE

         GROUP=METADATA_FILE_INFO
            PRODUCT_CREATION_DATE_TIME = 1999-06-04T11:36:48Z
            STATION_ID = "EDC"

         END_GROUP=METADATA_FILE_INFO

                  /*------------------------------*/
                  /*     Product  Metadata    */
                  /*------------------------------*/

         GROUP = PRODUCT_METADATA
            PRODUCT_TYPE = "L0R"
            SPACECRAFT_ID = “Landsat7”
            SENSOR_ID = “ETM+”
            ACQUISITION_DATE =  1999-01-31
            STARTING_PATH = 029
            STARTING_ROW = 036
            ENDING_ROW = 037
            TOTAL_WRS_SCENES = 2.04
            NUMBER_OF_SCANS = 744
```

```
            STARTING_SUBINTERVAL_SCAN = 3000
            ENDING_SUBINTERVAL_SCAN = 3743
            BAND_COMBINATION = “123456678”
            PRODUCT_UL_CORNER_LAT = 35.4950
            PRODUCT_UL_CORNER_LON = –105.2278
            PRODUCT_UR_CORNER_LAT =  35.2036
            PRODUCT_UR_CORNER_LON = –103.2219
            PRODUCT_LL_CORNER_LAT = 32.5736
            PRODUCT_LL_CORNER_LON= –106.0103
            PRODUCT_LR_CORNER_LAT = 32.292
            PRODUCT_LR_CORNER_LON = –104.0697
            BAND1_GAIN = "H"
            BAND2_GAIN = "H"
            BAND3_GAIN = "H"
            BAND4_GAIN = "H"
            BAND5_GAIN = "H"
            BAND6_GAIN_F1= "L"
            BAND6_GAIN_F2= "H"
            BAND7_GAIN = "H"
            BAND8_GAIN = "H"
            BAND1_FILE_NAME =             “L71EDC119903122010_B10.991551136”
            BAND2_FILE_NAME =             “L71EDC119903122010_B20.991551136”
            BAND3_FILE_NAME =             “L71EDC119903122010_B30.991551136”
            BAND4_FILE_NAME =             “L71EDC119903122010_B40.991551136”
            BAND5_FILE_NAME =             “L71EDC119903122010_B50.991551136”
            BAND6_FILE_NAME_F1 =          “L71EDC119903122010_B60.991551136”
            BAND6_FILE_NAME_F2 =          “L71EDC219903122010_B60.991551136"
            BAND7_FILE_NAME =             “L71EDC219903122010_B70.991551136"
            BAND8_FILE1_NAME =            “L71EDC219903122010_B81.991551136"
            IC_DATA_FILE_NAME_F1 =        “L71EDC119903122010_CAL.991551136"
            IC_DATA_FILE_NAME_F2 =        “L71EDC219903122010_CAL.991551136"
            SCAN_OFFSETS_FILE_NAME_F1 =   “L71EDC119903122010_SLO.991551136"
            SCAN_OFFSETS_FILE_NAME_F2 =   “L71EDC219903122010_SLO.991551136"
            MSCD_FILE_NAME_F1 =           “L71EDC119903122010_MSD.991551136”
            MSCD_FILE_NAME_F2 =           “L71EDC219903122010_MSD.991551136”
            PCD_FILE_NAME_F1 =            “L71EDC119903122010_PCD.991551136”
            PCD_FILE_NAME_F2 =            “L71EDC219903122010_PCD.991551136”
            METADATA_FILE_NAME_F1 =       “L71EDC119903122010_MTA.991551136”
            METADATA_FILE_NAME_F2 =       “L71EDC219903122010_MTA.991551136”
            METADATA_PS_FILE_NAME =       “L71EDC119903122010_MTP.991551136”
            CPF_FILE_NAME =            “L7CPF19990101_19990331_01.991551136”
            GEOLOCATION_FILE_NAME =       “L71EDC119903122010_GEO.991551136”
            HDF_DIR_FILE_NAME =           “L71EDC119903122010_HDF.991551136”

         END_GROUP = PRODUCT_METADATA

END_GROUP = ECS_METADATA_FILE

END
```

5.3.5 Calibration Parameter File

The CPF is stored as ASCII text that conforms to the ODL syntax. A complete description of this file currently exists in the *Landsat 7 Calibration Parameter File Definition* (see Section 1.4, Applicable Document 3. This document can be found on the IAS document server at http://ltpwww.gsfc.nasa.gov/IAS/htmls/review.html.

The CPF was created using the Vdata interface and specifying a single field 65,536 bytes long. Three Vdata table entries of this size are required to hold the CPF contents. Three Vdata reads would therefore be required to read the file into memory. An alternate and perhaps preferred way to manipulate the file is with an ODL interpreter. The CPF, like other product components is an external element that allows for other forms of file access using non-HDF tools.

5.3.6 Vgroup Definitions

The Vgroup structure was designed to associate related HDF data objects. Any HDF data object (e.g., Vdata, SDSs, attributes) can be included in an HDF Vgroup definition. Vgroups employ Vgroup names and Vgroup classes for characterizing a collection of data objects and for searching purposes. Three classes are recognized for the 0R product: image data, correction data, and metadata.

The HDF Vgroup interface consists of routines for accessing and getting information about the 0R product Vgroups. This information is stored in the HDF data directory.

The Vgroups used to relate the different component or data objects that make up a complete Level 0R scene product are presented in Table 5–8.

Table 5–8. Vgroup Definition for the Landsat 7 0R Product (1 of 2)

Vgroup Name	Vgroup Class	Data Object Contents		Description
		Object Name	Type	
Scene_Data_30m	Image_Data	"L7Xsss1nYYDOYHHuuv.B10"	SDS	ETM+ band 1 30m data
		"L7Xsss1nYYDOYHHuuv.B20"	SDS	ETM+ band 2 30m data
		"L7Xsss1nYYDOYHHuuv.B30"	SDS	ETM+ band 3 30m data
		"L7Xsss1nYYDOYHHuuv.B40"	SDS	ETM+ band 4 30m data
		"L7Xsss1nYYDOYHHuuv.B50"	SDS	ETM+ band 5 30m data
		"L7Xsss2nYYDOYHHuuv.B70"	SDS	ETM+ band 7 30m data
		"L7Xsss1nYYDOYHHuuv.GEO"	Vdata	Geolocation table
Scene_Data_60m	Image_Data	"L7Xsss1nYYDOYHHuuv.B60"	SDS	ETM+ band 6 60m low-gain data
		"L7Xsss2nYYDOYHHuuv.B60"	SDS	ETM+ band 6 60m high gain data
		"L7Xsss1nYYDOYHHuuv.GEO"	Vdata	Geolocation table
Scene_Data_15m	Image_Data	"L7Xsss2nYYDOYHHuuv.B81"	SDS	ETM+ band 8 15m data, one or more segment product
		"L7Xsss2nYYDOYHHuuv.B82"	SDS	ETM+ band 8 15m data, two or more segment product
		"L7Xsss2nYYDOYHHuuv.B83"	SDS	ETM+ band 8 15m data, three segment product
		"L7Xsss1nYYDOYHHuuv.GEO"	Vdata	Geolocation table

Table 5–8. Vgroup Definition for the Landsat 7 0R Product (2 of 2)

Vgroup Name	Vgroup Class	Data Object Contents		Description
		Object Name	Type	
IC_Data_30m	Calibration_Data	“L7Xsss1nYYDOYHHuuv.C10”	SDS	IC data band 1 30m
		“L7Xsss1nYYDOYHHuuv.C20”	SDS	IC data band 2 30m
		“L7Xsss1nYYDOYHHuuv.C30”	SDS	IC data band 3 30m
		“L7Xsss1nYYDOYHHuuv.C40”	SDS	IC data band 4 30m
		“L7Xsss1nYYDOYHHuuv.C50”	SDS	IC data band 5 30m
		“L7Xsss2nYYDOYHHuuv.C70”	SDS	IC data band 7 30m
		“L7Xsss1nYYDOYHHuuv.GEO”	Vdata	Geolocation table
IC_Data_60m	Calibration_Data	“L7Xsss1nYYDOYHHuuv.C60”	SDS	IC data band 6 60m – low gain
		“L7Xsss2nYYDOYHHuuv.C60”	SDS	IC data band 6 60m – high gain
		“L7Xsss1nYYDOYHHuuv.GEO”	Vdata	Geolocation table
IC_Data_15m	Calibration_Data	“L7Xsss2nYYDOYHHuuv.B80”	SDS	IC data band 8 30m data
		“L7Xsss1nYYDOYHHuuv.GEO”	Vdata	Geolocation table
Scan_Line_Offsets_30m	Correction_Data	“L7Xsss1nYYDOYHHuuv.O10”	Vdata	Scan line offsets band 1
		“L7Xsss1nYYDOYHHuuv.O20”	Vdata	Scan line offsets band 2
		“L7Xsss1nYYDOYHHuuv.O30”	Vdata	Scan line offsets band 3
		“L7Xsss1nYYDOYHHuuv.O40”	Vdata	Scan line offsets band 4
		“L7Xsss1nYYDOYHHuuv.O50”	Vdata	Scan line offsets band 5
		“L7Xsss2nYYDOYHHuuv.O70”	Vdata	Scan line offsets band 7
		“L7Xsss2nYYDOYHHuuv.GEO”	Vdata	Geolocation table
Scan_Line_Offsets_60m	Correction_Data	“L7Xsss1nYYDOYHHuuv.O60”	Vdata	Scan line offsets band 6 low
		“L7Xsss2nYYDOYHHuuv.O60”	Vdata	Scan line offsets band 6 high
		“L7Xsss1nYYDOYHHuuv.GEO”	Vdata	Geolocation table
Scan_Line_Offsets_15m	Correction_Data	“L7Xsss2nYYDOYHHuuv.O80”	Vdata	Scan line offsets band 8
		“L7Xsss1nYYDOYHHuuv.GEO”	Vdata	Geolocation table
PCD	Correction_Data	“L7Xsss1nYYDOYHHuuv.PCD”	Vdata	PCD—format 1
		“L7Xsss2nYYDOYHHuuv.PCD”	Vdata	PCD—format 2
MSCD	Correction_Data	“L7Xsss1nYYDOYHHuuv.MSD”	Vdata	MSCD—format 1
		“L7Xsss2nYYDOYHHuuv.MSD”	Vdata	MSCD—format 2
Product_Metadata	Metadata	“L7Xsss1nYYDOYHHuuv.MTA”	Vdata	Metadata—format 1
		“L7Xsss2nYYDOYHHuuv.MTA”	Vdata	Metadata—format 2
		“L7Xsss1nYYDOYHHuuv.MTP”	Vdata	Metadata—product specific
CPF	Parameter_Data	“L7CPFYYYYMMDD_YYYYMMDD.nn”	Vdata	IAS calibration parameter file

Section 6. Product Packaging

The first file on streamed media (e.g., 8 mm) is the product-specific metadata created by ECS. Its lead-off position allows for instantaneous product recognition without encountering any data overhead. Similar rationale was employed in placing the HDF Data Directory as file number two. This file is followed by the LPS metadata, PCD, MSCD, scan-line offsets, the CPF, IC data, and the band files.

Section 7. Software Tools

A variety of public domain software tools are available for processing the 0R distribution product in either an HDF-EOS, HDF, or independent computing environment.

7.1 NCSA HDF Libraries

HDF is a library- and platform-independent data format for the storage and exchange of scientific data. It includes Fortran and C calling interfaces and utilities for analyzing and converting HDF data files. HDF is developed and supported by NCSA and is available in the public domain.

The HDF library contains two parts: the base library and the multifile library. The base library contains a general purpose interface and application-level interfaces, one for each data structure type. Each application-level interface is specifically designed to read, write, and manipulate one type. The general purpose interface contains functions, such as file I/O, error handling, memory management, and physical storage. HDF library functions can be called from C or Fortran user application programs.

HDF source code for UNIX, Virtual Memory Storage (VMS), Windows NT/95, and Macintosh is available via anonymous file transfer protocol (ftp) from http://hdf.ncsa.uiuc.edu/obtain.html. HDF reference manuals, user guides, release notes, and newsletters are web accessible at http://hdf.ncsa.uiuc.edu.

7.2 HDF-EOS Libraries

HDF-EOS is standard HDF with ECS conventions and metadata added. The principal distinction is the specification of three geolocation data types: point, grid, and swath, which allow the file contents to be queried by Earth coordinates and time using the HDF-EOS application programming interface (API). The Landsat 7 0R distribution product does not employ either of these data structures. However, any application that makes use of the HDF-EOS API will, as a consequence of linking to the API, have access to the NCSA native base libraries that can be used to access the distribution 0R product.

EOSView is a file-viewing tool developed for the ECS project to examine and verify HDF and HDF-EOS data files. This tool enables users of EOS data products to view the contents of HDF files and individual objects via straightforward product access and display tools. Supported record types for viewing and display capability include images, multidimensional arrays, text, Vdatas, and Vgroups. EOSView users see the underlying HDF structures and are prompted for which parts of the structure they wish to view.

Users of the Landsat 7 0R product may also find the Science Data Production (SDP) Toolkit useful for follow-on processing. The SDP Toolkit consists of a set of fully tested, and reliable C and Fortran language functions, customized for application to ECS product generation software. Of particular interest to Landsat 7 data users is the ODL parser, which allows for reading, writing, and manipulating product metadata and the digital elevation model software tools.

The SDP Toolkit and HDF-EOS libraries are available via anonymous ftp from edhs1.gsfc.nasa.gov. Because this software was developed under a NASA contract and is intended for the use of EOS instrument teams and science investigators, access to download it is password protected. The password may be obtained by E-mail to pgstlkit@eos.hitc.com.

7.3 ODL Parser

The ODL parser (Version 1.0) incorporated into the SDP Toolkit was originally implemented by the University of Colorado's Laboratory for Atmospheric and Space Physics (LASP). The Jet Propulsion Laboratory enhanced the ODL parser in building their Planetary Data System. The improved ODL software (Version 2.1) is now maintained by LASP and is available via anonymous ftp from miranda.colorado.edu (IP address: 128.128.137.33).

Version 2.1 or later should be particularly useful to those operating in a non-HDF-EOS environment. The software stands alone and can be used to read the 0R metadata external elements and the CPF.

Section 8. Examples of HDF Programs

8.1 HDF Data Directory Listing

A variety of tools exist for examining the contents of a 0R distribution product. For example, the NCSA-developed hdp utility provides quick and general information about all objects in the specified HDF file. It lists the contents of HDF files at various levels with different details and can dump the data of one or more specific objects in the file. See Section 1.4, Applicable Document 8 for usage details.

A second tool is the EOSView file viewing tool developed for the ECS project for examining and verifying HDF and HDF-EOS data files. This tool enables the user of EOS data products to view the contents of HDF files and individual objects by providing the user with the ability to read and display appropriately all metadata fields and data objects. All data objects present in the 0R product are supported. EOSView users will see the underlying HDF structures and will be prompted for the parts of the structure they wish to view. Additional details can be found in Section 1.4, Applicable Document 13.

A third solution involves exploiting the IAS tools developed for reading, writing, and examining a 0R product. For example, the C code that follows dumps the HDF data directory in a more useful form than the hdp utility.

8.1.1 IAS Data Directory Viewing Tool

```
/*************************************************************************
                    Landsat 7 Image Assessment System (IAS) Software
                              Property of the U.S. Government
                                   NASA/GSFC/Code 510
*************************************************************************
```

UNIT NAME: readHDFDir.c

PURPOSE: Dump out the HDF directory vgroup information for a Volume V 0R product.

INVOCATION METHOD: readHDFDir -f <p_HDFDirectoryFile>

RETURN VALUE: Type = int

Value	Description
EXIT_SUCCESS	Task exit normally
EXIT_FAILURE	Task exited abnormally

ARGUMENT LIST:

Name	Type	Use	Description
-f	char *	I	File name option
p_HDFDirectoryFile	char *	I	HDF directory file

EXTERNAL FILE/RECORD/DBTABLE REFERENCES:

Name	Use	Description
HDF DAAC files	I	HDF file

EXTERNAL VARIABLES:

Source	Name	Type	Use	Description
getopt.h	optarg	char *	I	Points to the start of the option argument
getopt.h	opterr	int	I	Error number

EXTERNAL UNIT/MACRO/PROCEDURE/FUNCTION REFERENCES:

Name	Description
xxx_ReadHDFDirectory	Open, read in all directory index information, and close the HDF file
XXX_FREE_HDFDIRECTORY	Free HDF directory memory

ABNORMAL TERMINATION CONDITIONS, ERROR MESSAGES:
HDF error

ASSUMPTIONS, CONSTRAINTS, RESTRICTIONS:
Reading a DAAC Volume V Distribution Product file

DEVELOPMENT HISTORY

Author	Change-ID	Release	Date	Description of Change
J. Kerich	N/A	R2.0	11/04/97	Original Implementation

NOTES: readHDFDir -f L71EDC139617207013_HDF.973091707

Unit readHDFDir PDL:

```
        Initialize error flag to FALSE
1       DOWHILE more arguments to extract
                Call getopt() to get the next argument
                DOCASE argument
2               CASE file name:
                        Save p_HDFDirectoryFile file name
3               DEFAULT:
                        Set error flag to TRUE
                ENDDO
4       ENDDO
```

```
5       IF error flag is set THEN
                Print out error message
                RETURN EXIT_FAILURE
6       ENDIF
        Call xxx_ReadHDFDirectory() to open, read in all directory index information, and close
          the file
7       IF HDF error THEN
                Print out error message
                RETURN EXIT_FAILURE
8       ENDIF
        Print out HDF directory information
9       DOFOR all rows
                Print the row out
10      ENDDO
        XXX_FREE_HDFDIRECTORY to free HDF directory memory
        RETURN EXIT_SUCCESS
End Unit readHDFDir
*******************************************************************************/
/* System headers */
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>

/* Local headers */
#include <hdf.h>
#include <mfhdf.h>
#include <xdb_Defines.h>
#include <xxx_HDFDirectory.h>
#include <xxx_Types.h>

/* Macros */
#define OUTPUT_PATH    "/u01/iasdev/kerich/N2J3K3J2/"

/* Global variables */
extern char *optarg;
extern int opterr;

/* Main */
int main(int argc, char *argv[])
{
        xxx_HDFDirectoryControl_TYPE *p_HDFDirectoryControl;
```

```
char     ErrorMessage[XDB_ORAERRMSGLEN];

char     PathName[XXX_MAXPATH_SIZE] = {""};

int      i,k;

const char *p_HEstring;
int32   DataType;
int32   Rank;
int32   DimensionSizes[MAX_VAR_DIMS];
int32   nattrs;    / number of attributes /
char    vdataName[VGNAMELENMAX+1];
char    SDSName[VGNAMELENMAX+1];
int32   Interlace;
int32   vdataSize;
char    fields[80];
int32   Count;
int      c = 0;
boolean ErrorFlag = FALSE;

opterr = 0;
while ((c = getopt(argc, argv, "f:")) != -1) {
        switch(c) {
        case 'f':
                (void)strcpy(PathName, optarg);
                break;

        case '?':
                ErrorFlag = TRUE;
                break;
        }
}

if (ErrorFlag || PathName[0] == '\0') {
        (void)fprintf(stderr, "\nUsage: %s -f HDFDir\n", argv[0]);
        (void)fprintf(stderr, "\t\t[-f HDF directory file]\n");

        return(EXIT_FAILURE);
}

if ((p_HDFDirectoryControl = xxx_ReadHDFDirectory(PathName, XXX_INDEX_LISTING,
ErrorMessage)) == NULL)
{
        (void)printf("Can't read in HDFDirectory files:  %s\n", ErrorMessage);
        exit(EXIT_FAILURE);
}

(void)printf("---------------------------------------\n");
(void)printf("\nHDF directory statistics\n");
(void)printf("---------------------------------------\n");
for (k=0; k< p_HDFDirectoryControl->Count; k++)
{
```

```
        (void)printf("Vgroup Name=%s\n", p_HDFDirectoryControl-
          >p_HDFDirectory[k].VgroupName);
        (void)printf("Vgroup Class=%s\n", p_HDFDirectoryControl-
          >p_HDFDirectory[k].VgroupClass);
        (void)printf("Number Entries=%d\n", p_HDFDirectoryControl-
          >p_HDFDirectory[k].NumberEntries);

        if (p_HDFDirectoryControl->p_HDFDirectory[k].NumberEntries)
        {
                for (i=0; i < p_HDFDirectoryControl->p_HDFDirectory[k].NumberEntries; i++)
                {
                        (void)printf("          Object Name          ref       tag\n");
                        (void)printf("     ------------------------- ---------- ----------\n");
                        (void)printf("     %26s %10d %10d\n",
                          p_HDFDirectoryControl->p_HDFDirectory[k].p_ObjectInfo[i].ObjectNam
                          p_HDFDirectoryControl->p_HDFDirectory[k].p_ObjectInfo[i].ref,
                          p_HDFDirectoryControl->p_HDFDirectory[k].p_ObjectInfo[i].tag);
                }
        }
        (void)printf("\n");

}

XXX_FREE_HDFDIRECTORY(p_HDFDirectoryControl);


if ((p_HDFDirectoryControl = xxx_ReadHDFDirectory(PathName, XXX_CAL_BAND2,
ErrorMessage)) == NULL)
{
        (void)printf("Can't read in HDFDirectory files:  %s\n", ErrorMessage);
        exit(EXIT_FAILURE);
}
(void)printf("Vgroup Count=%d\n", p_HDFDirectoryControl->Count);
(void)printf("Vgroup Name=%s\n", p_HDFDirectoryControl-
  >p_HDFDirectory[0].VgroupName);
(void)printf("Vgroup Class=%s\n", p_HDFDirectoryControl-
  >p_HDFDirectory[0].VgroupClass);
(void)printf("Number Entries=%d\n", p_HDFDirectoryControl-
  >p_HDFDirectory[0].NumberEntries);

if (SDgetinfo(p_HDFDirectoryControl->sds_id, SDSName, &Rank, DimensionSizes,
&DataType, &nattrs) == FAIL)
{
        (void)strcpy(ErrorMessage, "Can't get file information: ");
        p_HEstring = HEstring((hdf_err_code_t)HEvalue(EXIT_FAILURE));
        (void)strcat(ErrorMessage, p_HEstring);

        (void)SDendaccess(p_HDFDirectoryControl->sds_id);
        (void)SDend(p_HDFDirectoryControl->SDId);

        XXX_FREE_HDFDIRECTORY(p_HDFDirectoryControl);

        exit(EXIT_FAILURE);
}
```

```
(void)printf("---------------------------------------\n");
(void)printf("SDS Name=%s\n", SDSName);
(void)printf("Rank=%d\n", Rank);
(void)printf("Dimension sizes %dX%d\n", DimensionSizes[0],
   DimensionSizes[1]);
(void)printf("Data type=%d\n", DataType);
(void)printf("Number attrubutes=%d\n", nattrs);
(void)printf("---------------------------------------\n\n\n");

(void)SDendaccess(p_HDFDirectoryControl->sds_id);
(void)SDend(p_HDFDirectoryControl->SDId);

XXX_FREE_HDFDIRECTORY(p_HDFDirectoryControl);

if ((p_HDFDirectoryControl ==x xx_ReadHDFDirectory(PathName, XXX_CPF,
  ErrorMessage))
== NULL)
{
        (void)printf("Can't read in HDFDirectory files:  %s\n", ErrorMessage);
        exit(EXIT_FAILURE);
}
(void)printf("Vgroup Count=%d\n", p_HDFDirectoryControl->Count);
(void)printf("Vgroup Name=%s\n", p_HDFDirectoryControl-
  >p_HDFDirectory[0].VgroupName);
(void)printf("Vgroup Class=%s\n", p_HDFDirectoryControl-
  >p_HDFDirectory[0].VgroupClass);
(void)printf("Number Entries=%d\n", p_HDFDirectoryControl-
  >p_HDFDirectory[0].NumberEntries);

if (VSinquire(p_HDFDirectoryControl->vdataId, &Count, &Interlace, fields, &vdataSize,
vdataName) == FAIL)
{
        (void)strcpy(ErrorMessage, "Error inquiring MSCD file: ");
        p_HEstring = HEstring((hdf_err_code_t)HEvalue(EXIT_FAILURE));
        (void)strcat(ErrorMessage, p_HEstring);
        (void)printf("%s\n", ErrorMessage);

        VSdetach(p_HDFDirectoryControl->vdataId);
        Vend(p_HDFDirectoryControl->FileId);
        (void)Hclose(p_HDFDirectoryControl->FileId);

        XXX_FREE_HDFDIRECTORY(p_HDFDirectoryControl);
        exit(EXIT_FAILURE);
}

(void)printf("---------------------------------------\n");
(void)printf("Vdata Name=%s\n", vdataName);
(void)printf("Interlace Type=%s\n", XXX_INTERLACE_STRING(Interlace));
(void)printf("Bytes Per Logical Record=%d\n", vdataSize);
(void)printf("Number of Records=%d\n",Count);
(void)printf("Field name=%s\n",fields);
(void)printf("---------------------------------------\n\n\n");
```

```
        VSdetach(p_HDFDirectoryControl->vdataId);
        Vend(p_HDFDirectoryControl->FileId);
        (void)Hclose(p_HDFDirectoryControl->FileId);


        XXX_FREE_HDFDIRECTORY(p_HDFDirectoryControl);


        return (EXIT_SUCCESS);
}
```

8.1.2 0R Product Data Directory Listing

Execution of the code presented above with the command

```
        IAS-> readHDFDir -f L71EDC139617207013_HDF.973091707
```

results in a complete HDF 0R product directory listing as follows:

```
HDF directory statistics
----------------------------------------
Vgroup Name=Scene_Data_30m
Vgroup Class=Image_Data
Number Entries=7
        Object Name                    ref        tag
    --------------------------                  ----------  ----------
      L71EDC139617207013.B10        15        702
        Object Name                    ref        tag
    --------------------------                  ----------  ----------
      L71EDC139617207013.B20        27        702
        Object Name                    ref        tag
    --------------------------                  ----------  ----------
      L71EDC139617207013.B30        47        702
        Object Name                    ref        tag
    --------------------------                  ----------  ----------
      L71EDC139617207013.B40        75        702
        Object Name                    ref        tag
    --------------------------                  ----------  ----------
      L71EDC139617207013.B50       111        702
        Object Name                    ref        tag
    --------------------------                  ----------  ----------
      L71EDC239617207013.B70       267        702
        Object Name                    ref        tag
    --------------------------                  ----------  ----------
      L71EDC139617207013.GEO      1450       1962

Vgroup Name=Scene_Data_60m
Vgroup Class=Image_Data
Number Entries=3
        Object Name                    ref        tag
    --------------------------                  ----------  ----------
      L71EDC139617207013.B60       155        702
        Object Name                    ref        tag
    --------------------------                  ----------  ----------
```

```
        L71EDC239617207013.B60       207       702
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.GEO       1450      1962

Vgroup Name=Scene_Data_15m
Vgroup Class=Image_Data
Number Entries=2
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC239617207013.B81       335       702
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.GEO       1450      1962

Vgroup Name=Scan_Line_Offsets_30m
Vgroup Class=Correction_Data
Number Entries=7
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.O10       26        1962
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.O20       46        1962
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.O30       74        1962
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.O40       110       1962
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.O50       154       1962
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC239617207013.O70       334       1962
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.GEO       1450      1962

Vgroup Name=Scan_Line_Offsets_60m
Vgroup Class=Correction_Data
Number Entries=3
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.O60       206       1962
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC239617207013.O60       266       1962
          Object Name                ref       tag
    ------------------------         ----------  ----------
        L71EDC139617207013.GEO       1450      1962
```

Vgroup Name=Scan_Line_Offsets_15m
Vgroup Class=Correction_Data
Number Entries=2

Object Name	ref	tag
L71EDC239617207013.O81	410	1962

Object Name	ref	tag
L71EDC139617207013.GEO	1450	1962

Vgroup Name=PCD
Vgroup Class=Correction_Data
Number Entries=2

Object Name	ref	tag
L71EDC139617207013.PCD	1446	1962

Object Name	ref	tag
L71EDC239617207013.PCD	1447	1962

Vgroup Name=MSCD
Vgroup Class=Correction_Data
Number Entries=2

Object Name	ref	tag
L71EDC139617207013.MSD	1448	1962

Object Name	ref	tag
L71EDC239617207013.MSD	1449	1962

Vgroup Name=Product_Metadata
Vgroup Class=Metadata
Number Entries=3

Object Name	ref	tag
L71EDC139617207013.MTA	1451	1962

Object Name	ref	tag
L71EDC239617207013.MTA	1452	1962

Object Name	ref	tag
L71EDC139617207013.MTP	1454	1962

Vgroup Name=CPF
Vgroup Class=Parameter_Data
Number Entries=1

Object Name	ref	tag
L71996049IASCAL.A01	1453	1962

Acronyms and Abbreviations

0R	Level 0 reformatted (data)
6H	band 6, high gain
6L	band 6, low gain
ACCA	automated cloud cover assessment
ACS	Attitude Control System
ADS	angular displacement sensor data
API	application programming interface
ASCII	American Standard Code for Information Interchange
BCH	Bose-Chaudhuri-Hocquenghem
BER	bit error rate
CADU	channel access data unit
CCA	cloud cover assessment
CFPA	cold focal plane assembly
CPF	calibration parameter file
CPU	central processing unit
CRC	cyclic redundancy code
DAAC	Distributed Active Archive Center
DFCB	Data Format Control Book
ECI	Earth Center Inertial
ECS	EOSDIS Core System
EDC	EROS Data Center
EOL	end of line
EOS	Earth Observing System
EOSDIS	EOS Data and Information System
EROS	Earth Resources Observation Systems
ETM+	Enhanced Thematic Mapper Plus
FAC	full aperture calibrator
FHS	first half scan
ftp	file transfer protocol

GB	gigabyte
GMT	Greenwich Mean Time
HDF	Hierarchical Data Format
I/O	input/output
IAS	Image Assessment System
IC	internal calibrator
ICD	interface control document
IEEE	Institute of Electrical and Electronics Engineers
IGS	international ground station
IMU	internal measurement unit
ISO	International Organization for Standardization
km	kilometer
L1R	Level 1radiometrically corrected (data)
LASP	Laboratory for Atmospheric and Space Physics
LGS	Landsat Ground Station
LPS	Landsat Processing System
Mbps	megabit per second
ms	millisecond
MOC	Mission Operation Center
MSCD	mirror scan correction data
NASA	National Aeronautics and Space Administration
NCSA	National Center for Supercomputing Applications
ODL	Object Description Language
PCD	payload correction data
Q&A	quality and accounting
SDP	Science Data Production
SDS	Scientific Data Set
SHS	second half scan
SLD	scan line data
TBR	to be resolved
TBS	to be submitted

URL	Uniform Resource Locator
UTC	Universal Time Code
UT1	UTC corrected
VCDU	virtual channel data unit
VMS	Virtual Memory Storage
WRS	Worldwide Reference System